EML 4501 Spring 2020 – Group 13 Assisted Rehabilitative Kinematic (ARK) Cross Gawel, Tomas Riveron-Garcia, Jeremy Joseph, Jordan Pickering, Michael MacIsaac, Sarah Knapp, and Sean Pendergast

Abstract/Product Overview

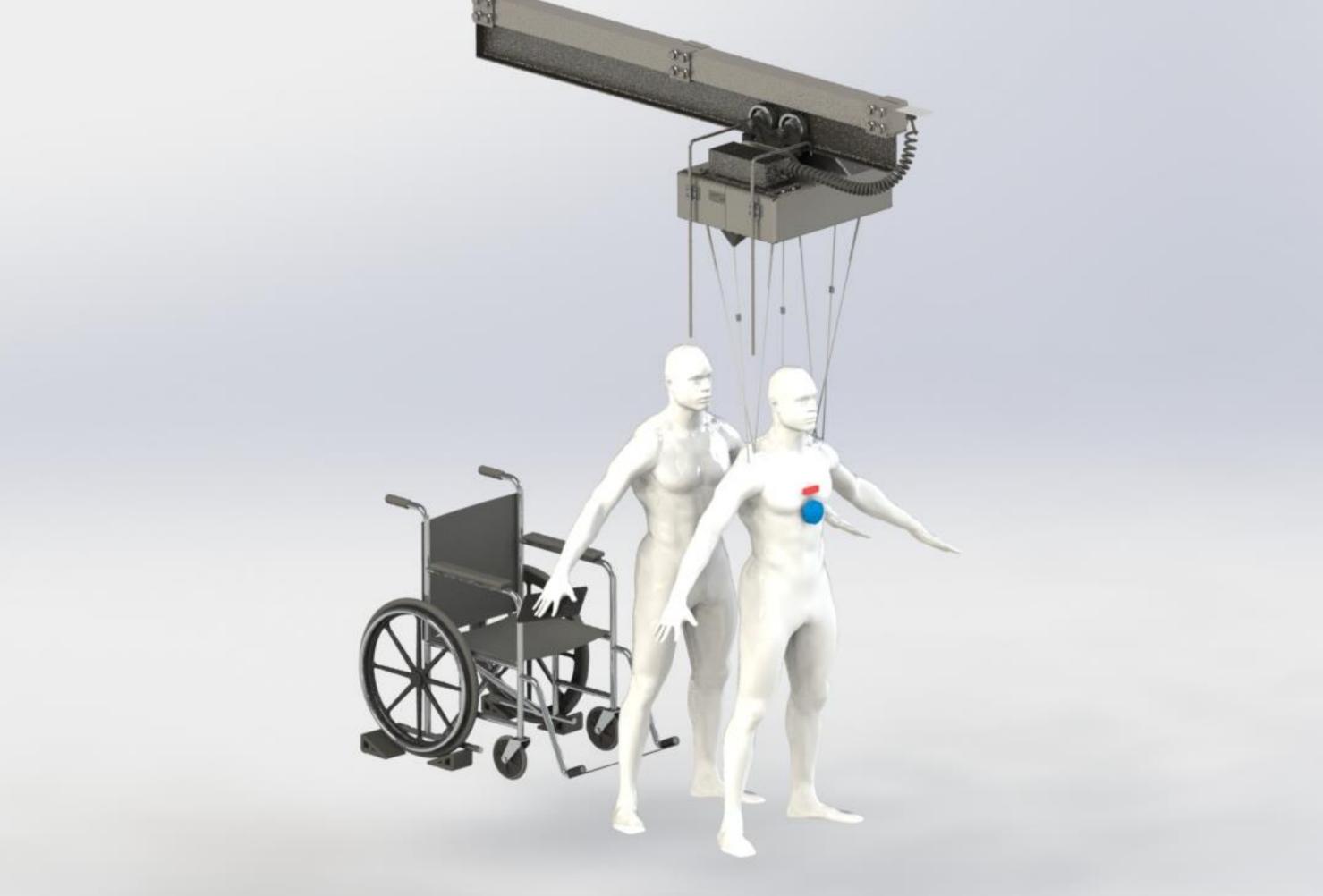
The Assisted Rehabilitative Kinematic (ARK) Device is a unique system design to help paraplegics use elliptical machines. The design features a ceiling mounted I-beam assembly, fitted with a trolley, trolley housing, power supply, and harness. The trolley system possesses two motors and a winch designed for supporting the weight of the user and the two motors have the capability of being continuously adjusted with a Raspberry Pi while the user is exercising. This trolley translates one-dimensionally across a specified portion of the I-beam to successfully lift the user from a wheelchair and into position above an elliptical training device. The rehabilitation specialist will be responsible for the movement of the user to the elliptical at a pace comfortable to both.

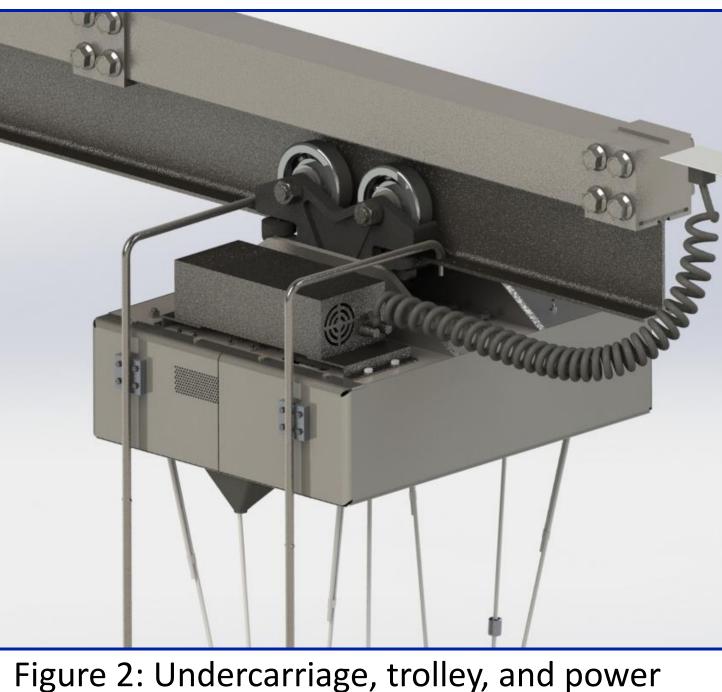
Cost Overview

- Off-the-self (OTS) Parts Cost: \$2,300.80
- Raw Material Cost: \$492.00
- Manufacturing and Labor Cost: \$1,345.62
- Energy Cost: \$0.17
- Assembly Labor Cost: \$53.31
- Total Cost: \$4,191.73

Customer Needs	1, 30	2	3, 9, 29	4, 10, 11, 15, 16, 17, 19, 20, 21	5, 6, 8, 25, 28	7, 12, 13, 14	22, 23, 26, 27	18	24
Requirement	Size (2'10" × 8')	Power (120 VAC and 15-amp)	Interference	Weight offset, support 100% weight (297 lb), maintain balance and offset during exercise, comfortable, variable (ability to adjust from 0 – 100% weight) and continuous offset weight (use of	Safety, FOS of 2, fail- safe catch (withstand impact force of 528 lbf), prevent hitting,	Transition User (1-2 ft/s)	Programmable with GUI and Features (single click with ¾ inch icons),		Cost (materials and OTS parts cost less than \$4,000)
Subsystem	Frame	Power	Whole system	Interior Undercarriage	years) Whole system, Cables, and Harness	Whole system	 indications (LED indicator) Interior Undercarriage, Motor Housing, and tablet. 	Ceiling Mount	Whole system
Feature	I-Beam and Trolley Floor Area (1'5" × 2'2")	Power Supply (12 DC, 110/220 ACV, and 80 Amps)	not have interference with the system, person, or ETS.	Winch, NEMAs, Cables, and Drivers/Controllers can adjust the variable weight offset, continuously, comfortably, left and right, vertically, and accommodate the full weight.	Safety cables, and harness emergency stop button.	Frame and trolley, winch, user aided, and trolley locking mechanism.	Motor drivers and controllers, Raspberry Pi, LED signals, and a		Material and OTS Part Cost: \$2,792.80

Figure 1: Full assembly showing the unique I-beam and trolley mechanism as well as the undercarriage and the wheelchair locking mechanism. The patient is wearing the emergency shutoff button and sensor that will attached to the harness and the aid is holding a tablet that will communicate with the motors.





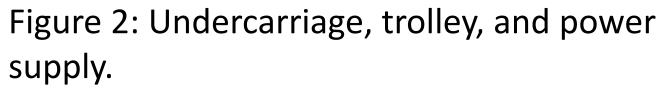
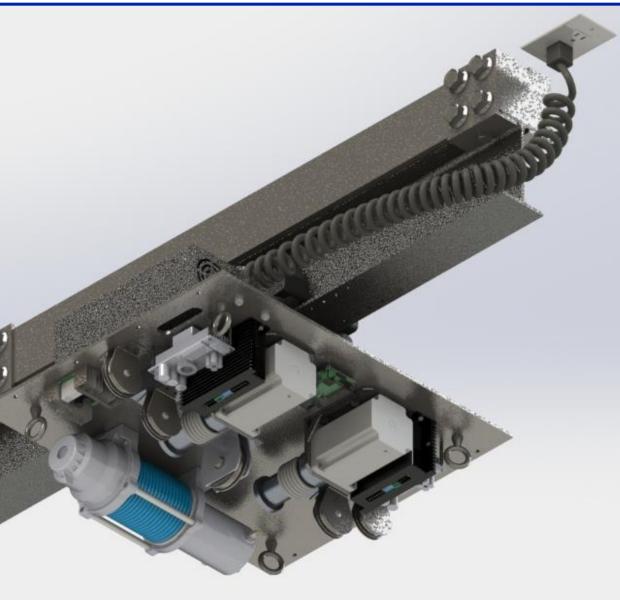


Figure 3: Interior of undercarriage showing the motors, driver, pullies, voltage booster, and Raspberry Pi.



FEA Undercarriage

- total NEMA)

Figure 4: Isometric view of static test with 325 lbf total on winch bolts and 120 lbf total on NEMA bolt holes. Deformation scale 281.

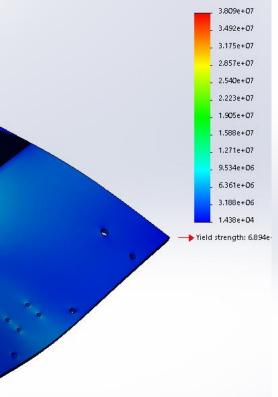
FEA I-Beam Analysis Static Test (360 lbf load) Maximum Von Mises Stress: 485.5 MPa Maximum Deformation: 0.2488 mm



scale 871.028.

Static Test (325 lbf total on winch and 120 lbf

Maximum Von Mises Stress: 38.09 MPa Maximum Deformation: 0.2165 mm Fatigue Test (10⁸ cycles or Infinite Life)



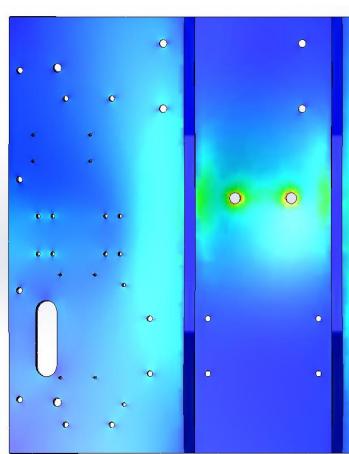


Figure 5: Top view of static test with 325 lbf total on winch bolts and 120 lbf total on NEMA bolt holes. Deformation scale: 281.

1.372e-06 1.248e-06 1.123e-06

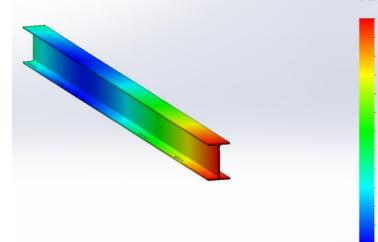


Figure 6-8: Isometric views of static test with 360 lbf located 17.875 in and 24.125 in from image nearside. From left to right: stress, displacement, and strain. Deformation