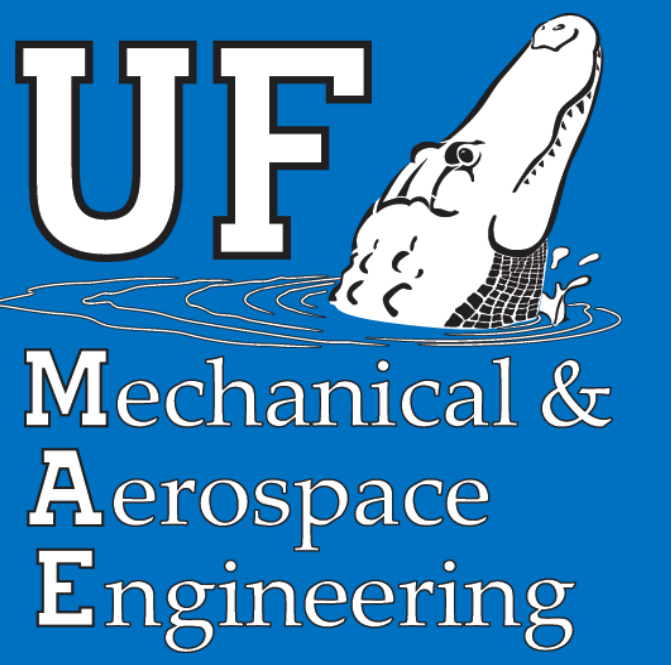


Dr. Clean Bioreactor

Group 10: Iratxe Astigarraga, Vidal Cruz Ramos, Garrett Doty, Jack Drohan, Vitan Georgievski, Salomon Molko, Denisse Pena-Valerio

Department of Mechanical and Aerospace Engineering, University of Florida



Abstract & Product Functionality

The Doctor Clean Bioreactor grows bacteria cultures with little to no additional work to the user. The sanitation system incorporated in the bioreactor will be able to safely dispose of culture materials and sanitize the equipment used, making the system ready for the next experiment. The well plates and conical tubes, still filled with cell culture media, are placed into a sanitation chamber that will cull the cell cultures and dispose of solid and liquid waste, leaving sanitized well plates and tubes for future use. The Dr. Clean Bioreactor uses a manipulator system to interact with the cell cultures and other system features, including a fluid handling system capable of providing nutrients to cultures, a shaker system capable of linear, orbital, and double orbital motions to aerate cultures, and a climate-controlled storage system. Optical density and fluorescent intensity measurements will be taken frequently to monitor cell growth within the enclosure. The assembly can maintain consistent temperature within the interior to protect electrical components as well as a reasonable temperature on the exterior to allow for movement of the overall system within a laboratory environment. The Doctor Clean Bioreactor was designed for parameters set by the UF Biofoundry and to fulfill customer needs metrics outlined by industry experts. Prioritization of meeting these needs and outperforming previous iterations of bioreactor designs is critical to design evaluation and future performance in the final down-selection stages of the project.

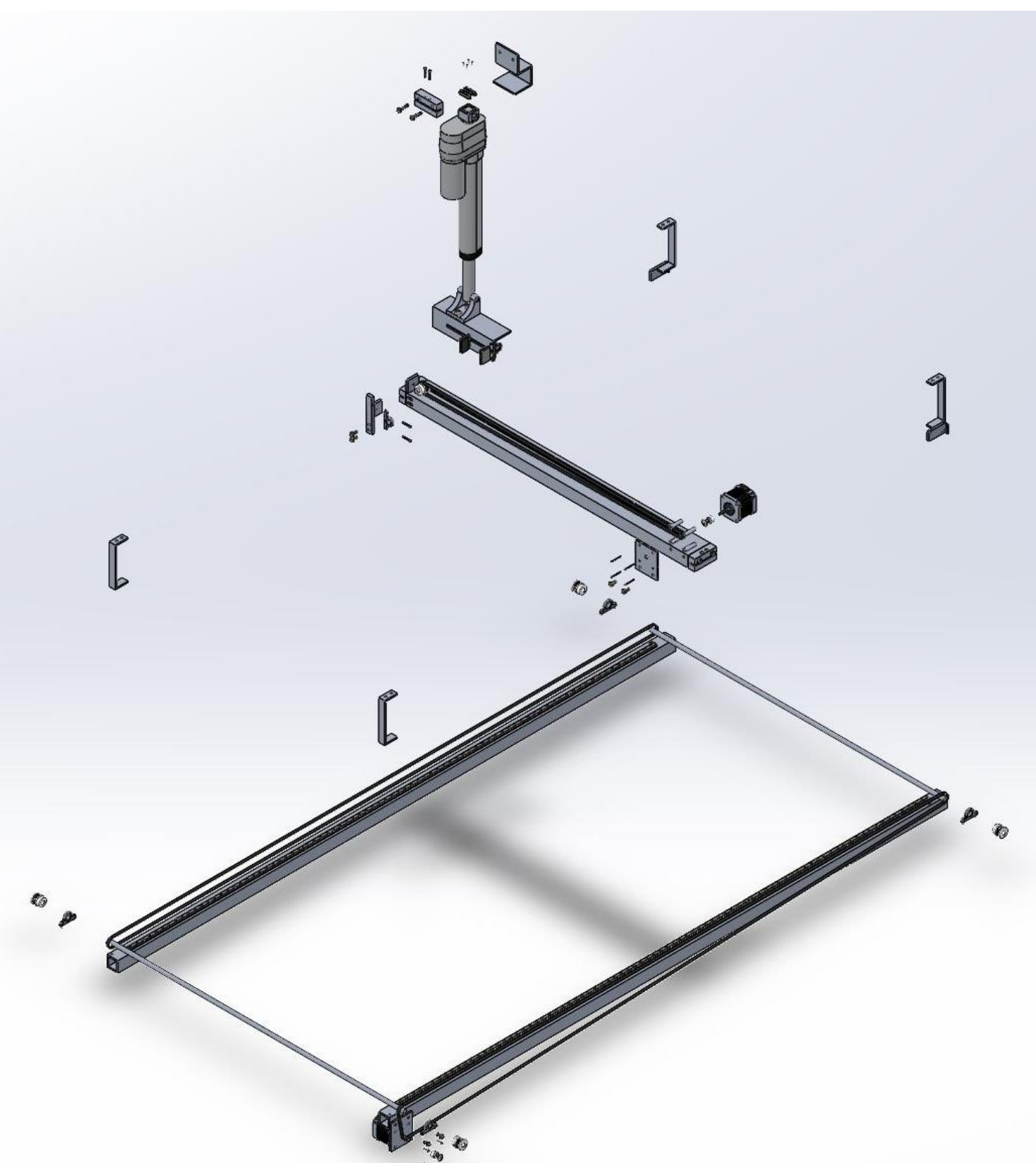
Cost

OTS Parts: \$7138.17
Modified OTS Parts: \$182.67
Raw Materials: \$1001.02

Manufacturing Labor: \$834.78
Energy Consumption: \$55.44
Assembly Labor: \$520.00

Manipulator

The manipulator subsystem is responsible for transporting well plates and conical test tubes across the entire structure. The system provides precise movement in the X, Y, and Z axes while securely gripping the well plates. The movement in the X and Y directions is actuated through Nema-17 stepper motors, which rotate timing belts and are part of a larger pulley system for each drive. To ensure precision, tensioning blocks have been added to each belt. Movement in the Z-direction is controlled by a 6 inch linear actuator which is connected to the gripper and the X drive on opposite ends. The gripper itself operates with a lead screw a moveable jaw, and a fixed jaw.



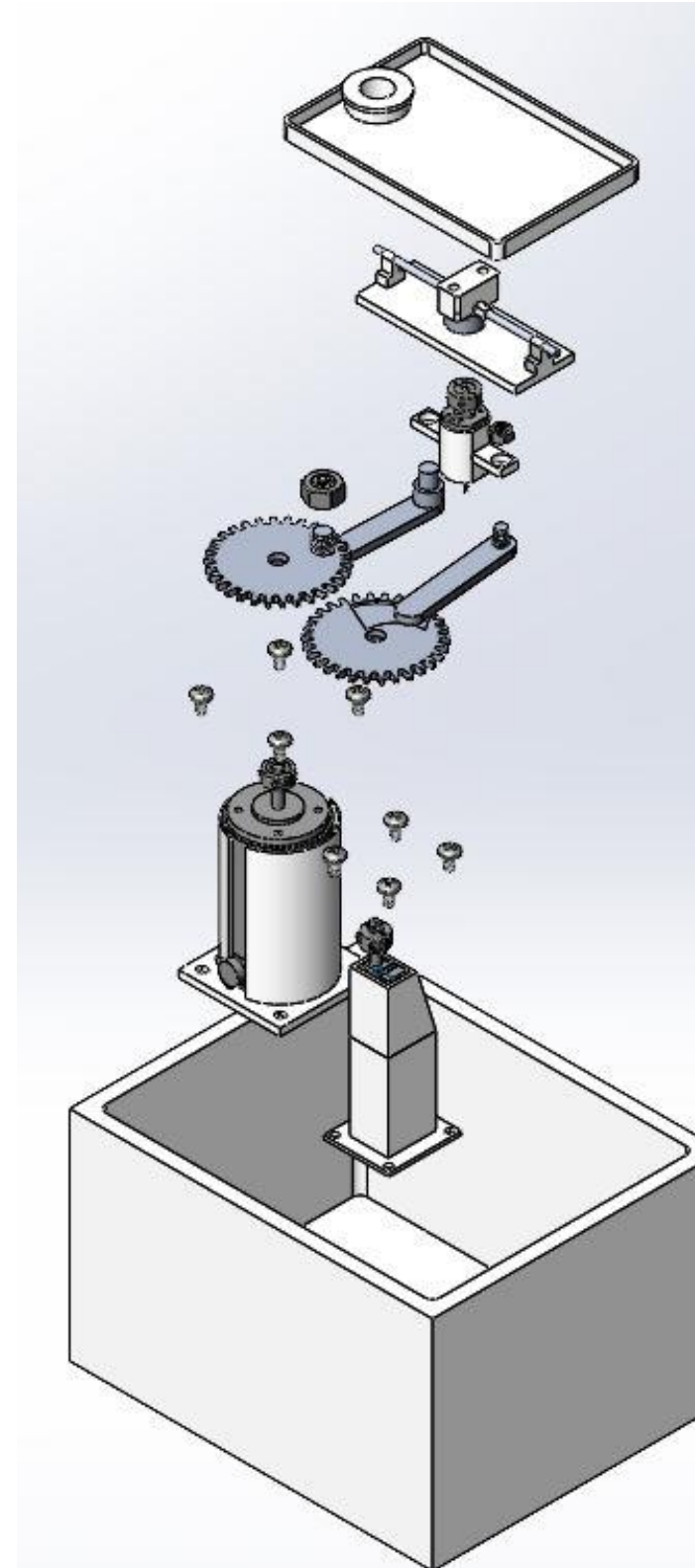
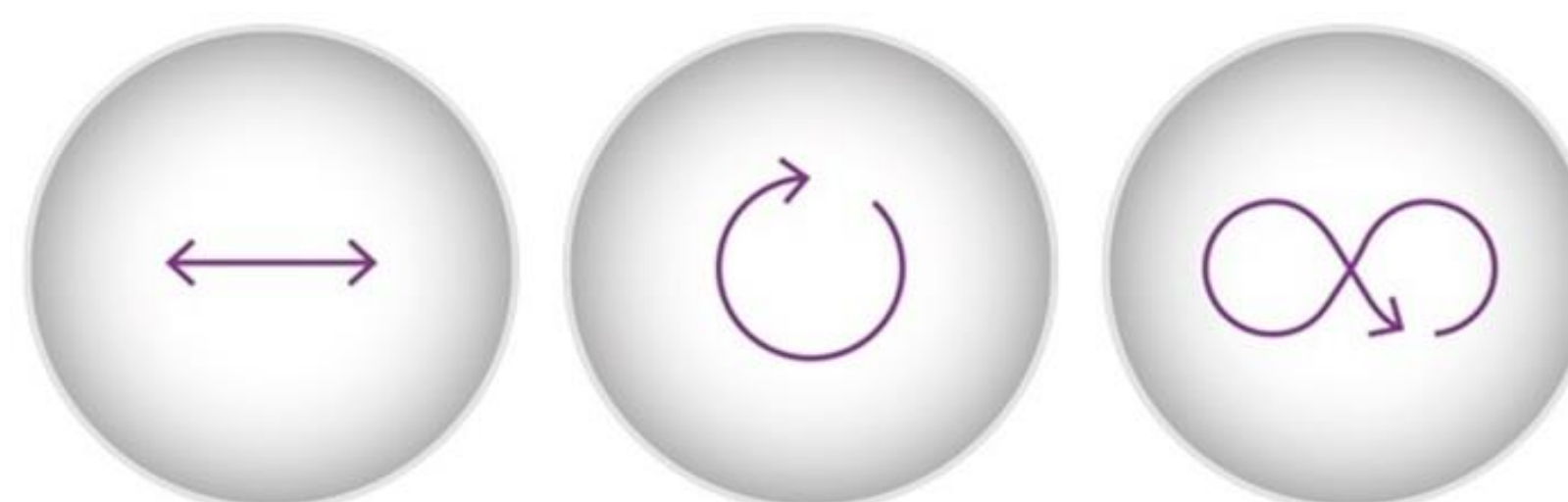
System Design and Key Features

- Self-Sterilizing
- OD/FI Measurements
- 3 Mixing Patterns
- Gas Liquid and Nutrient Injection
- Automated Manipulator
- Insulated with Temperature Control



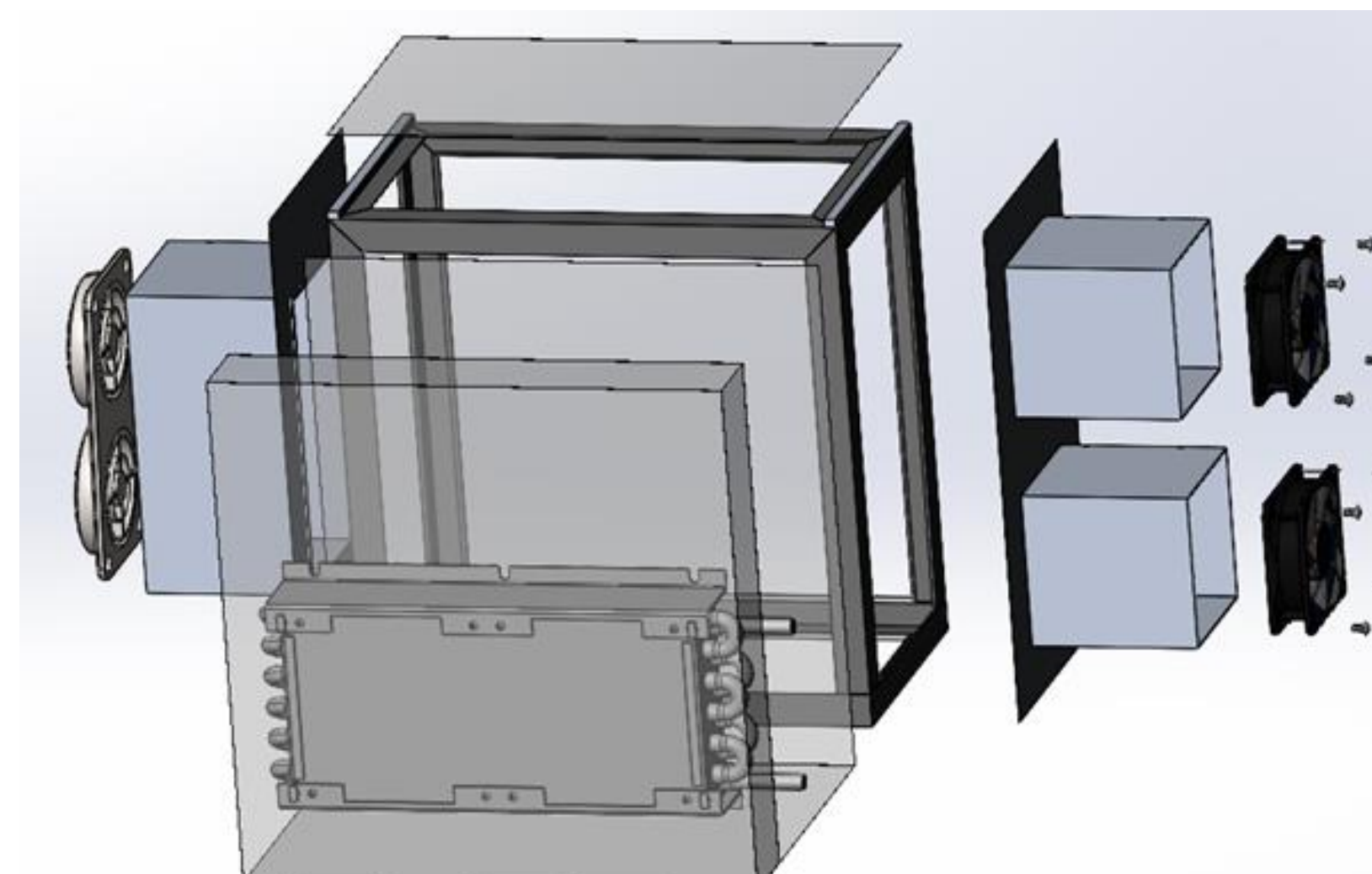
Shaker

The shaker system is capable of linear, orbital, and double orbital motion patterns to aerate cell cultures. Double orbital motion is created by using two gears with rods connected at a central point. A gear shifter disengages the second gear for single orbital motion, and a scotch yoke mechanism creates linear motion.



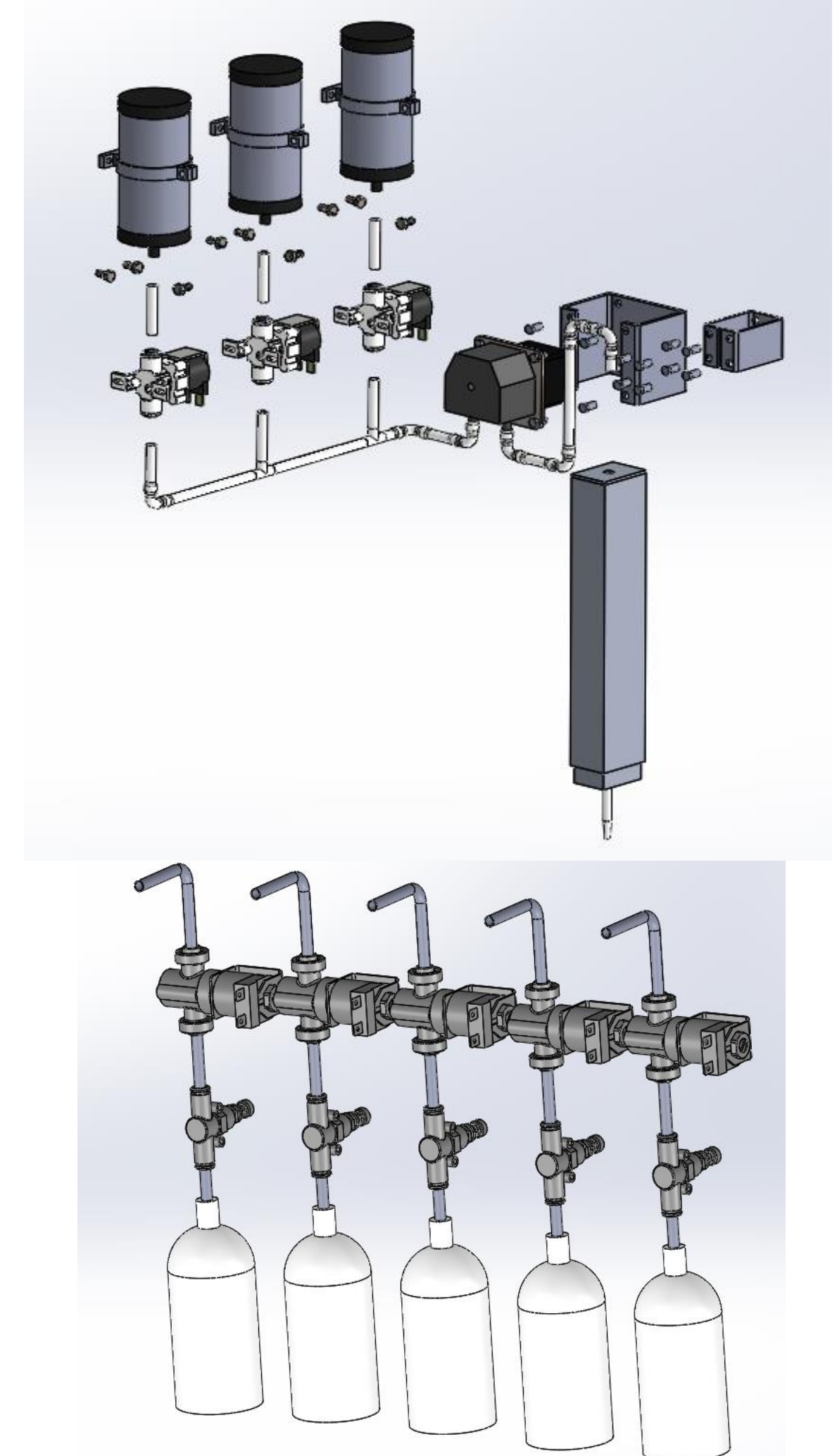
Environmental Management

This subsystem is principally responsible for the consistent heating and cooling capabilities exhibited to the bacterial cultures. This includes a controllable heat exchanger which is rated for the temperatures outlined in the customer metrics, with control parameters from user inputted commands. The environment insulates temperature variation from affecting the electrical components of the overall assembly while achieving necessary bacterial culture growth during experimentation



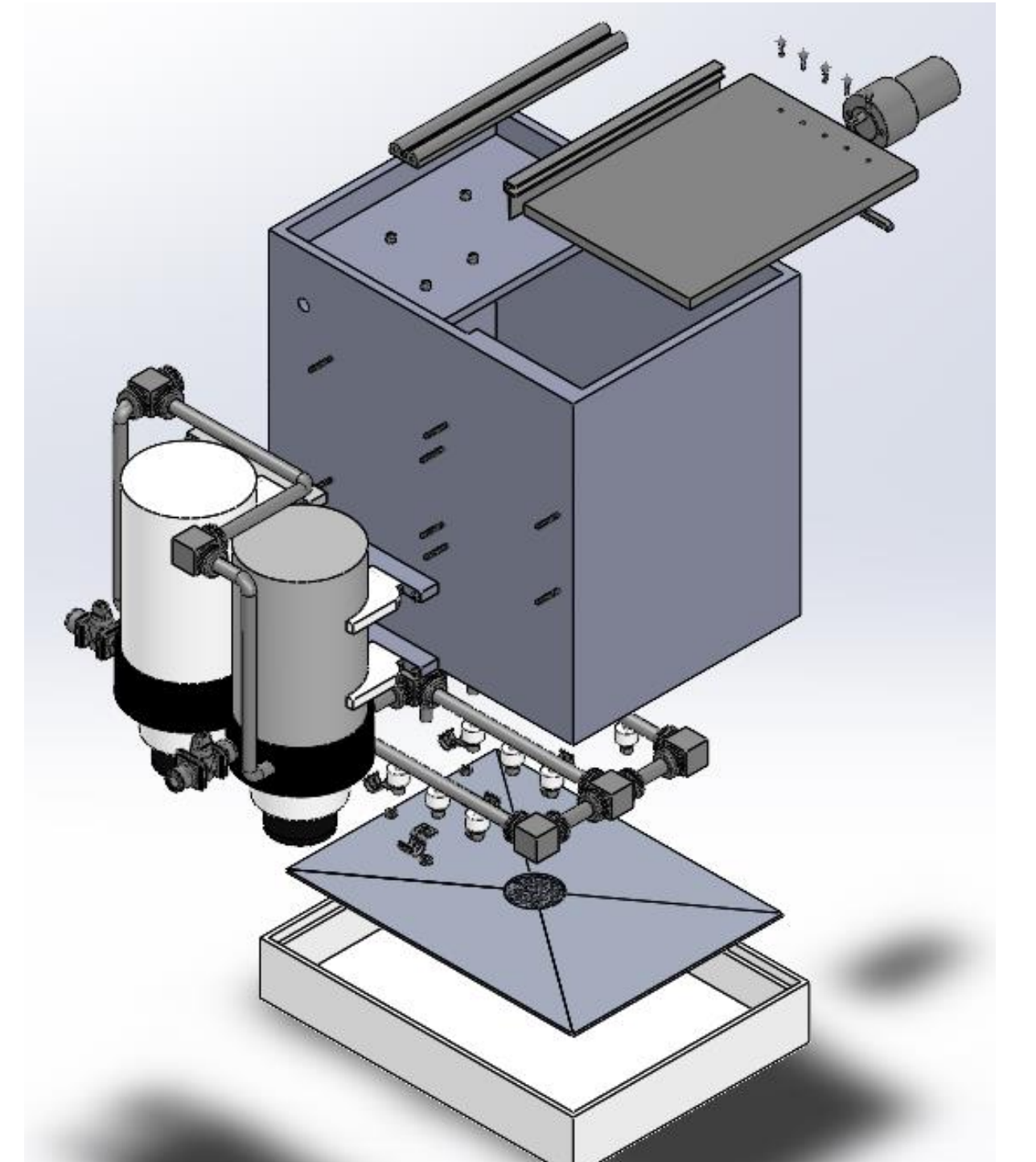
Fluid Handling

The fluid handling system addresses the needs of satisfactorily moving cultures suspended in liquid between compartments. The system includes three deposits, electromechanically controlled solenoid valves, a pump and a high accuracy dispensing valve, avoiding cross contamination. The air injection system is completely automated and is capable of injecting, regulating and measuring the composition of different gases. The system also includes a filtering and gas evacuation mechanism.



Sanitation

The sanitation subsystem consists of two fluid reservoirs (bleach and DI water) that are pumped into pipe sprayed through a nozzle into an enclosed structure to sterilize the well plates and tubes used while culling and disposing the bacteria after incubation. The base of the structure is 36x27 cm and consists of a drain and waste tray acting as a reservoir.



Controller

This subsystem uses 3 Arduino Uno Rev3s which handle the interaction between the processor and the motors, pumps, and anything that would require an on/off switch. The bioreactor mode is accomplished by directing the modified light bar onto the well plates. This light bar will have the standard yellow LEDs swapped out for RGB LEDs that can change the color to either red, green, or blue. The spectrometer probe will be mounted so that it takes measurements above the well plates or tubes using the manipulator arm as the guide.

