Multi-Chamber BioGator 8000



Linear Rails

Shaking

Mechanism

ABSTRACT: Group 7's goal was to design a system that maximizes the number of compartments, each capable of independent temperature control and gas composition regulation, that can be easily added if the budget were expanded. The vertical and modular design utilizes space on the bench top efficiently. A custom pipette with a linear actuator controls the flow of liquid into and out of the pipette for disbursement Replaceable tips are pressed on and off from a foam block as needed to eliminate cross-contamination. The linear rail system combines a claw for movement of samples and the pipetting system in threedimensional motion. Two linear rail systems supporting the shaking table are capable of linear, orbital, and double orbital shaking patterns. A custom holder for the well plates and conical tubes allows for the claw to pick up the samples to perform shaking, liquid disbursement, and OD/FI measurements outside of the compartment. A central chiller presents additional cooling capacity that can be used for multiple compartments. Within each enclosure, evaporative cooling comes from a heat exchanger while a cartridge heater supplies heat necessary to maintain the desired temperature. A fan beneath these elements disburses the heating and cooling evenly. The optical density and fluorescent intensity measurements are taken at the stationary laser beam and Photomultiplier tube (PMT) sensor combination. The movement mechanism maneuvers each sample between the two and the measurements are completed.

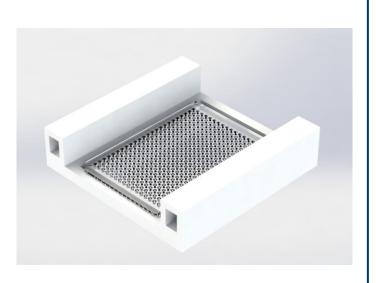
Group 7: Alexander Dominguez, Gabriel Dos Santos, Ali Elsaadany, Gabriela Faxas, Corinne O'Halloran, Garrett Oehlerking, Alejandro Ruiz, Ryan Streepey

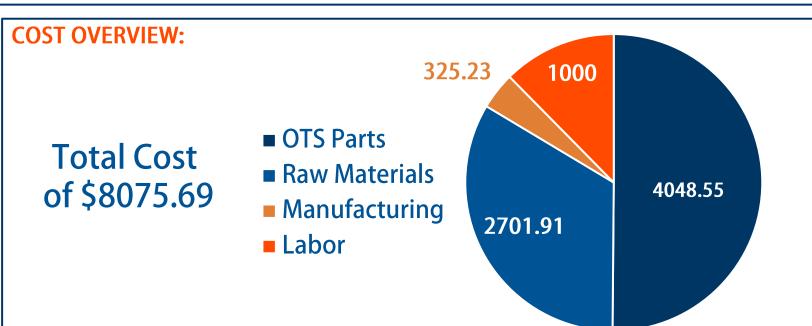
PRODUCT FUNCTIONALITY: This robot eliminates human intervention from cell culturing and OD/FI measurements. It is a fully autonomous device capable of various functions based on the customer needs. The user inserts the well plate, or the tray of conical tubes, into the compartment and places them into the custom holder that is designed to be able to connect with the robot arm inside the main compartment. Temperature can be adjusted inside the compartment within a range of 4 and 70 degrees Celsius through evaporative cooling and a heating element. A composition of gas can be added to the environment of the compartment to allow cell culturing. After having the cells live in this desired environment, the custom well plate is picked up by the robot arm and goes through different processes such as liquid control where liquid could be added using a pipette system. In addition, the cells needs to go through a shaking process where a designated area inside the main compartment is capable of various types of shaking. Finally, there is a stationary OD/FI measurement device that has full access to the well plate and allows for measurements that backs out the changed properties of the cells after going through the desired environment. This OD/FI system utilizes a laser beam, a filter, and a Photomultiplier tube. The device is capable of collecting measurements and keeping the well plates inside for up to two weeks.

CUSTOM SAMPLE HOLDER

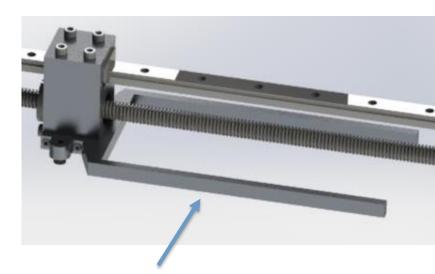
Custom holder for the well plates and conical tubes allow for our custom claw to pickup and transport samples

Clear bottom to aid in **OD/FI** measurements





MOVEMENT FOR LIQUID DISBURSEMENT



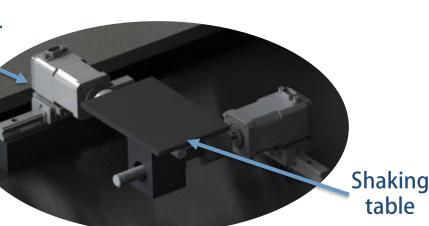
Custom claw stepper motor

Nema -17

Three Nema-14 stepper motors, each with a lead screw, and linear rails allow for three-dimensional motion

Custom claw picks up samples by utilizing custom made holders

Supplies movement for liquid disbursement, OD/FI measuring, and traveling to the shaking table



Shaking

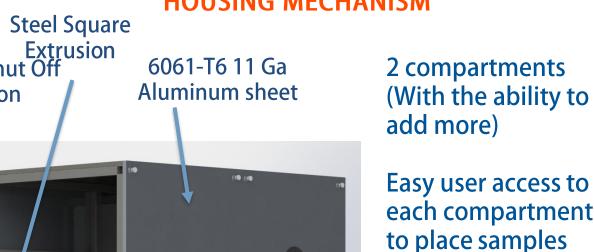
DISPLAY & USER INTERFACE



LCD screen displays visual indicators necessary to program the experiments.

Temperature controllers for each enclosure are displayed.

HOUSING MECHANISM



Cross-flow heat

exchanger

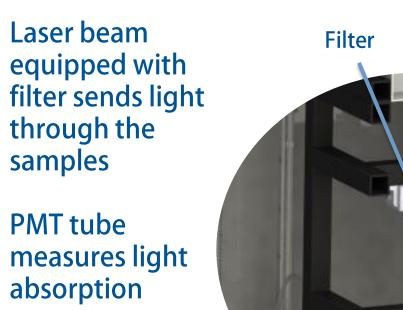
Easy access to waste compartment for disposal

inside

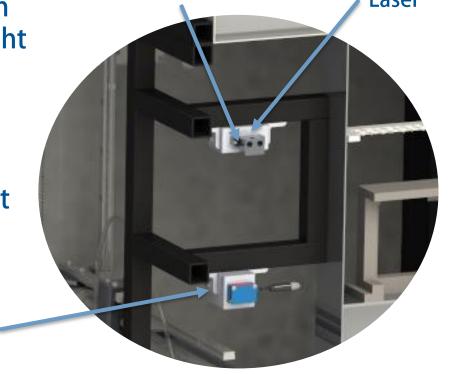
Thumbscrews on removal panels to reduce reach length

OD/FI MEASUREMENTS

Movement mechanism equipped with claw maneuvers samples between the stationary laser and Photomultiplier (PMT) tube combination.



Photomultiplier (PMT) tube



SHAKING MECHANISM

Two linear rail system capable of twodimensional motion

Controlled by 2 Nema-17 stepper motors

Capable of linear, orbital, and double orbital shaking patterns

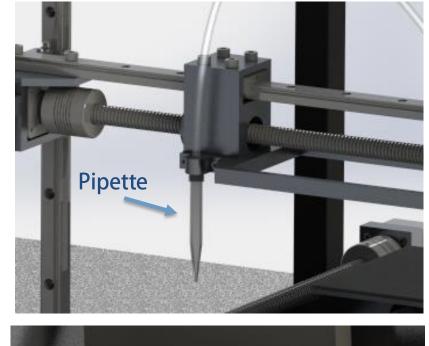
LIQUID CONTROL

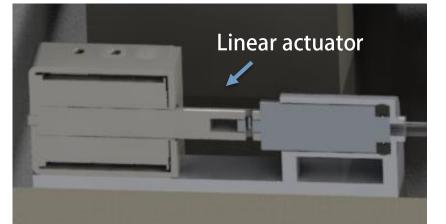
Custom pipette connected to a linear actuator controls flow of liquid in and out of the pipette

Replaceable tips are pressed on and off of the foam block to eliminate cross-contamination

Indentations on the tips compress rubber cylinder to lock on

Reservoir tank holds 1.18 L of required medium





TEMPERATURE CONTROL

Heat transfer from the 150 W cartridge heater to the environment achieves the 70°C requirement.

The central chiller provides cooled fluid that is run through the heat exchanger and achieves the 4°C requirement.

This design reaches the set temperature in just 11 minutes.

The fan, located beneath the heat exchanger, introduces forced convection to evenly distribute the heating/cooling.

Thermocouple Input/output ports of heat exchanger for chiller connection 150 W cartridge heater Fan / **White LED** mount lights Miner's lamp

GAS COMPOSITION

Butterfly valves equipped with sensors control injecting, measuring, and regulating the composition of gases:

N₂, O₂, CO₂, CH₄, H₂

5 input ports, one for each gas

Miner's lamp used to burn combustible exhaust gas

POWERING THE NEW ENGINEER

TO TRANSFORM THE FUTURE



Pipette Clamp

Herbert Wertheim College of Engineering UNIVERSITY of FLORIDA

