



Herbert Wertheim  
College of Engineering  
UNIVERSITY of FLORIDA

# Sunflower Heliostat

*By Electric Sunflower Technologies*

Section 13335, Group 2

K. Bauer, A. DeBoer, M. Itkin, B. Ortiz, J. Owens, J. Spillman, K. Todd

# Our Motivations

- Mechanical manipulation and clever design
- Sleep
- Want to have a job!
  - Satisfy customer needs



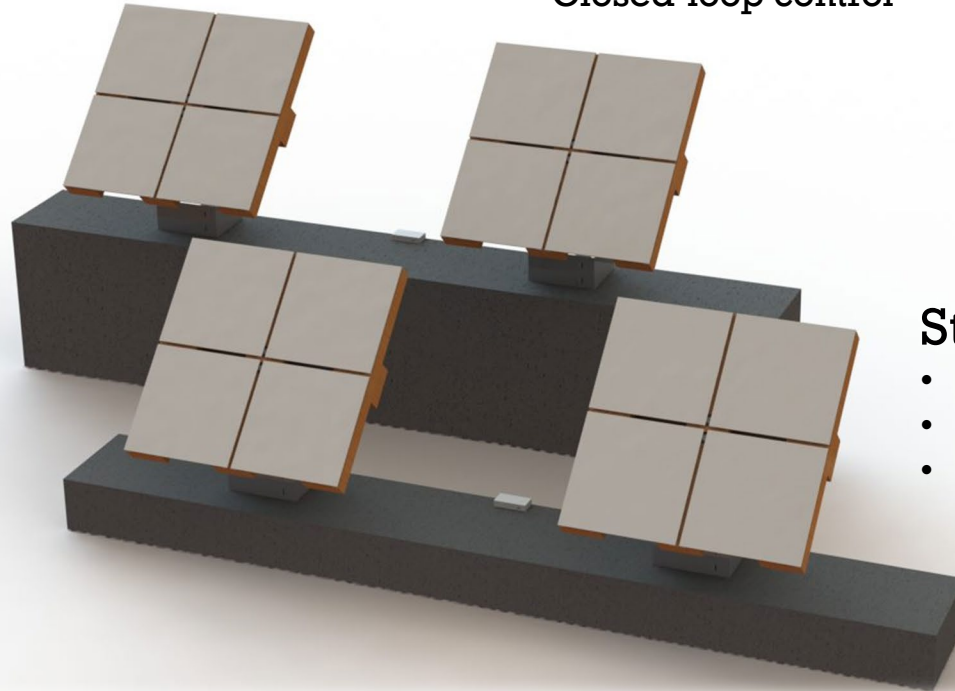
# Sunflower Heliostat

## Reflective Surface

- 176.41 W Thermal input
- 5,669 Modules to 1 MW
- 1,635 Suns of solar concentration

## Electronics

- Raspberry Pi 0W
- Sealed enclosures
- Closed-loop control



## Structure

- “Step and Stagger”
- Concrete base
- Bronze bushings

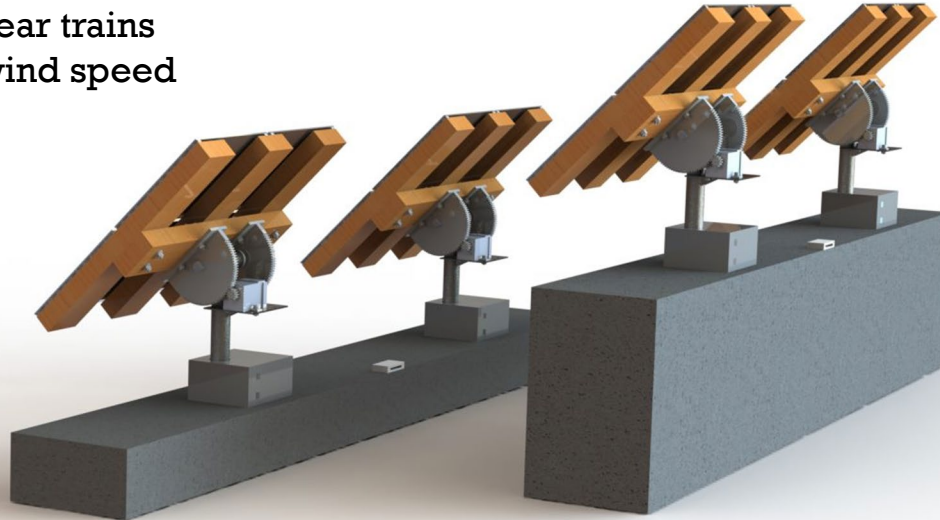
# Product Overview

## Motion

- Two axes of rotation
- High-torque gear trains
- 40 MPH max wind speed

## Reflective Backing

- Pressure treated 2" x 4" beams
- Pliable adhesive



# Reflective Surface

Customer Needs Addressed: 1, 2, 4, 7, 16, 17, 18

- Four **0.0625 m<sup>2</sup>** silvered annealed glass mirrors per heliostat
  - **3 mm** thick
- Heliostat reflective surface mass = **1.86 kg**
- Allows for easy handling and maintenance



# Reflective Surface

## Key Feature: Multi-Mirror

- Thermal input per module = **176.408 W**
  - 1 MW is obtained with **5,669 modules**

$$Q = G_{bt} A \eta_{opt}$$

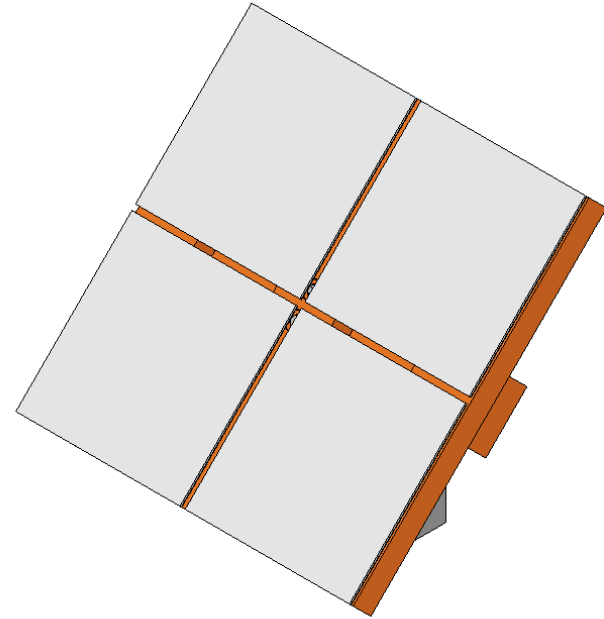
$$\eta_{opt} = 0.5 \eta_{ref}$$

$$G_{bt} = G_{bn} \cos \theta_{inc}$$

- Concentration ratio of **1,635 suns**

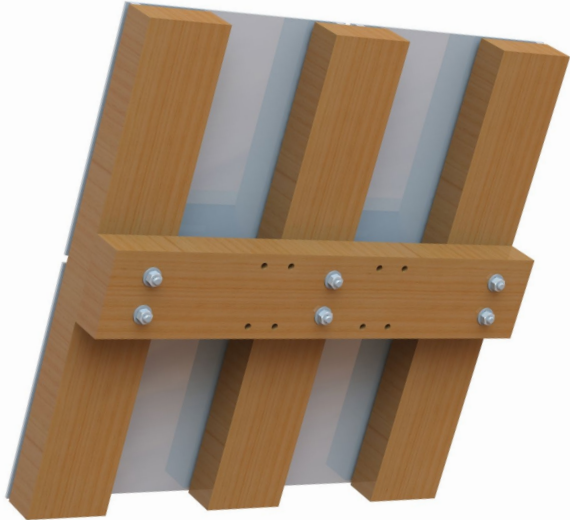
$$q_{solar} = G_{bn} C_{geo} \eta_{opt}$$

$$C_{geo} = \frac{A_{heliostats}}{A_{receiver}}$$



# Reflective Backing

Customer Needs Addressed: 1, 13, 14, 15



- 2" x 4" pressure-treated and kiln-dried cedar
- Max deflection = **0.017 mm**
  - Deflection of a composite cantilever beam
$$\delta = \frac{FL^3}{3EI}$$
- Mass = **2.39 kg**
- FOS for bending = **4.66**

# Reflective Backing

## Key Feature: Epoxy Adhesive

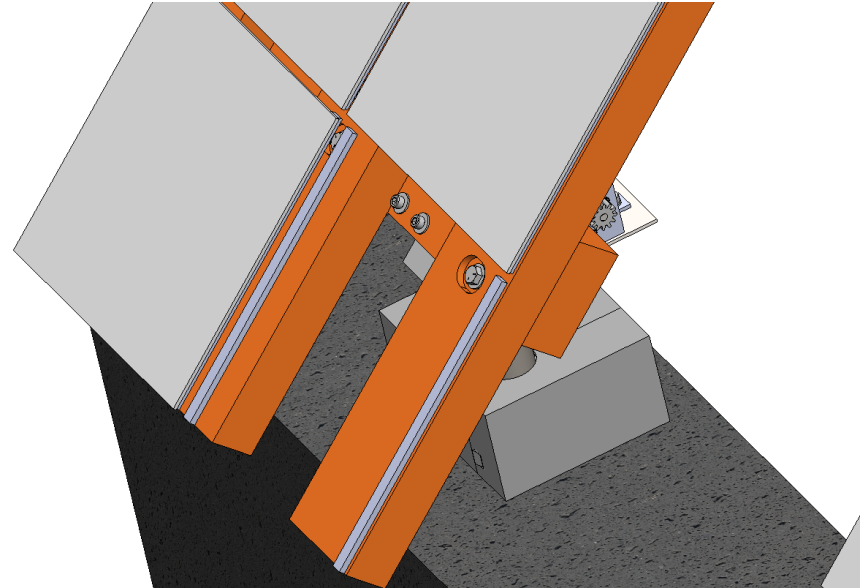
- Differences in thermal expansion causes internal stresses
- Epoxy is **6.31 mm** thick

$$\alpha_{wood} = 30 \times 10^{-6} \text{ } ^\circ\text{C}^{-1}$$

$$\alpha_{glass} = 9 \times 10^{-6} \text{ } ^\circ\text{C}^{-1}$$

$$\delta = \alpha \Delta T L$$

$$\delta_{epoxy} = \frac{\tau t}{G}$$





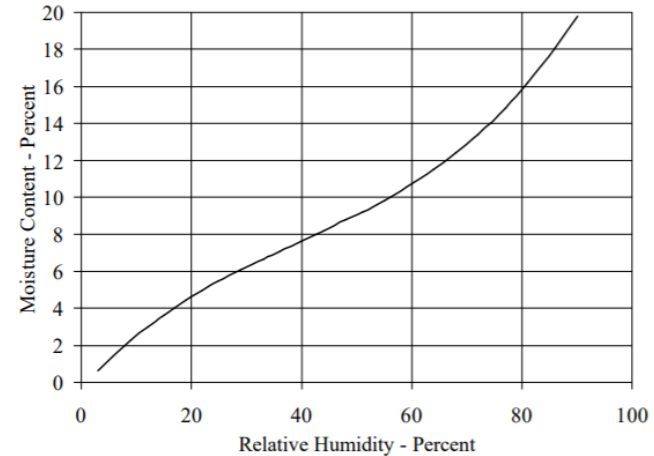
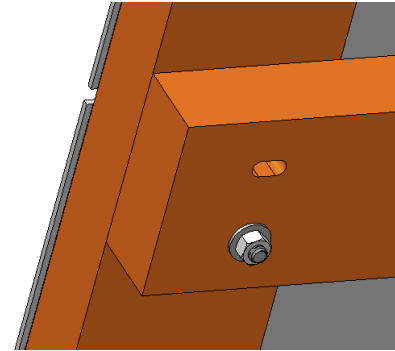
# Reflective Backing

## Key Feature: Fastener Slots

- Max deformation due to swelling or shrinking = **0.19 mm**

$$\Delta W = W \left( \frac{SC}{100} \right) \frac{\Delta mc}{30}$$

- Slots help deal with cracking near wood contact



Carl Eckelman: *The Shrinking and Swelling of Wood and Its Effect on Furniture*

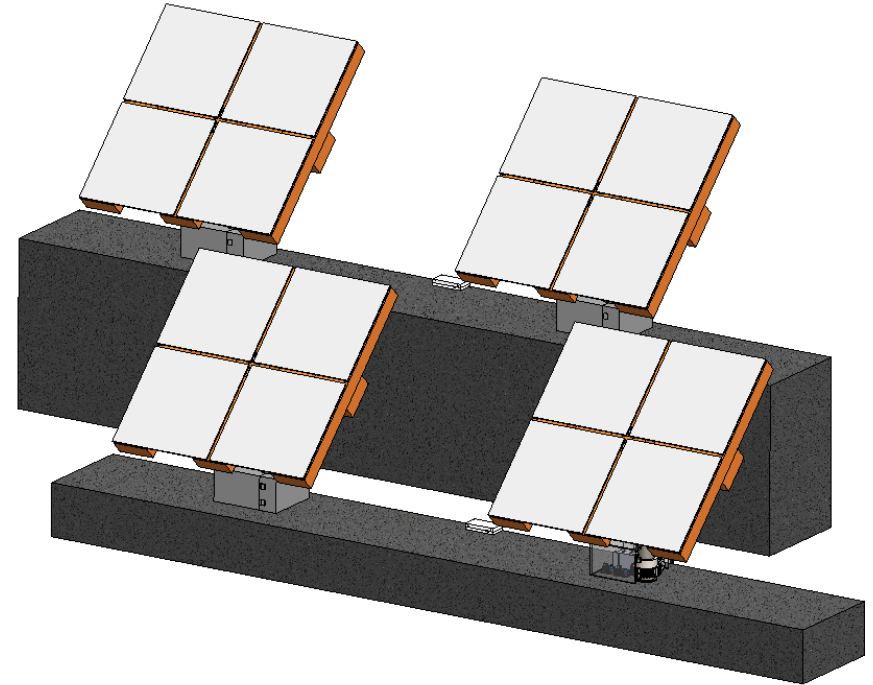
# Motion

Customer Needs Addressed: 4, 5, 7, 8, 13, 14, 15

- Tracks sun azimuthal and elevation angle
- High mechanical advantage = Low cost

Azimuth:  $\theta_1 \leq 330^\circ$

Elevation:  $\theta_2 \leq 65^\circ$



# Motion

## Torque Requirements: Worm Geartrain

### Friction

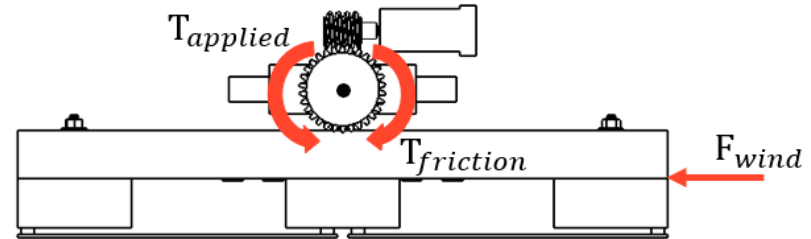
$$T_{bushing} = \mu_1 F_{wind} r$$

$$T_{slider} = \mu_2 W r$$

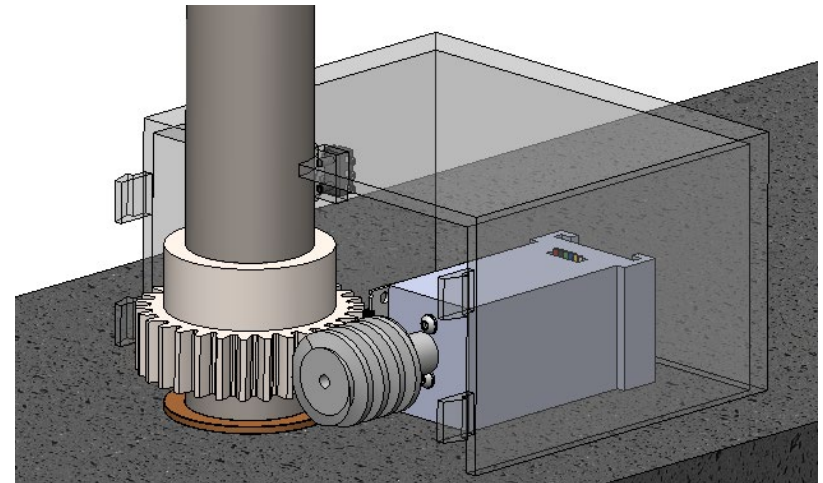
$$T_{friction} = T_{bushing} + T_{slider} = 3.85 \text{ lb} \cdot \text{in}$$

### Wind

$$T_{wind} = \frac{1}{2} \rho v^2 A_{2 \times 4} * R = 4.42 \text{ lb} \cdot \text{in}$$



$$T_{applied} = \left( \frac{30 \text{ teeth}}{1 \text{ teeth}} \right) * 2.5 \text{ lb} \cdot \text{in} = 75 \text{ lb} \cdot \text{in}$$

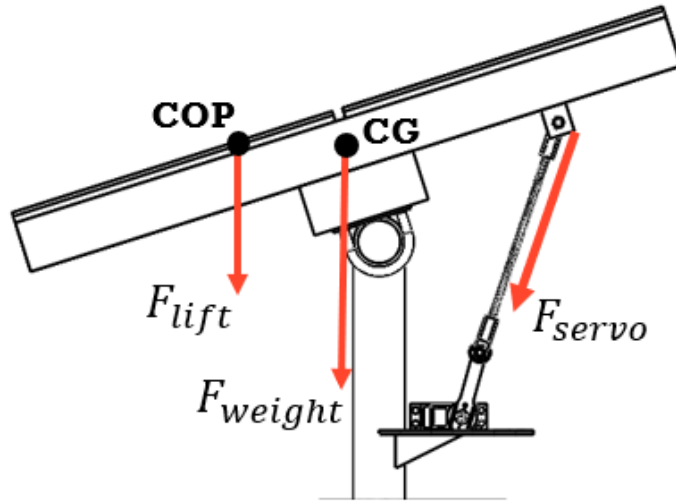


**Max Torque Required: 8.27 lb · in**

# Motion

## Torque Requirements: Initial Servo Design

- Operational wind speed limited by motor torque

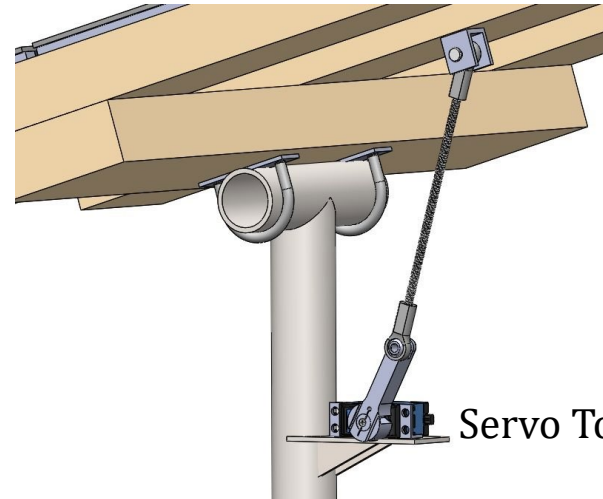


$$F_{lift} = \frac{1}{2} \rho v^2 A \sin \theta C_L = 20.7 \text{ lbs}$$

$$C_L = \cos \alpha \sin \alpha (K_p \cos \alpha + \pi \sin \alpha) = 1.68$$

$$F_{weight} = 9.37 \text{ lbs}$$

$$T_{applied} \geq T_{wind} + T_{weight}$$

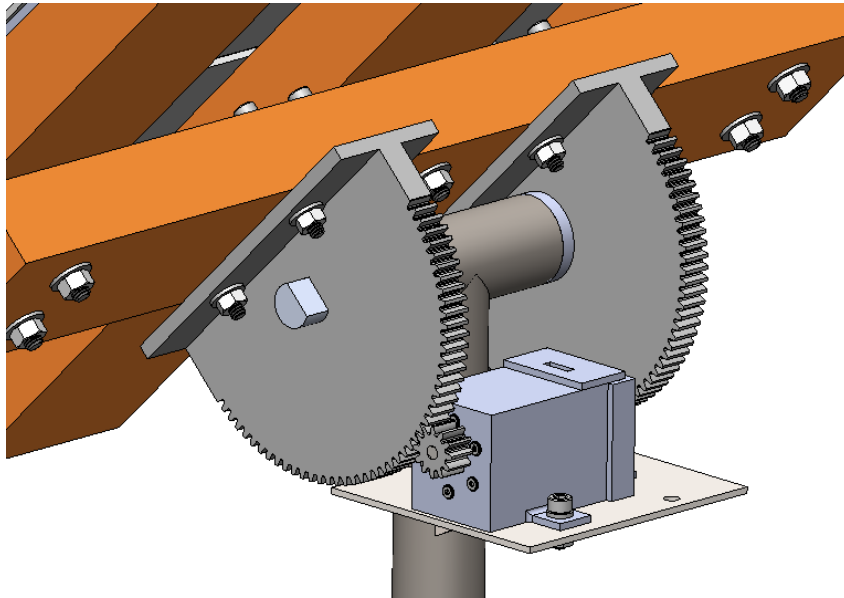


Servo Torque = 13 lb · in

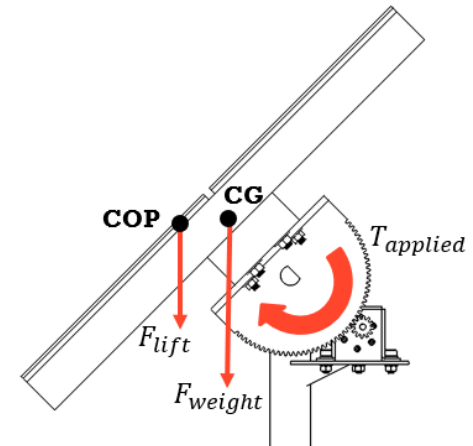
**Max Torque Required: 92.3 lb · in**

# Motion

## Key Feature: High Torque Gear Assembly



- 8:1 Gear ratio
- Reduced motor costs by 62%
- Max wind speed = **48 MPH**

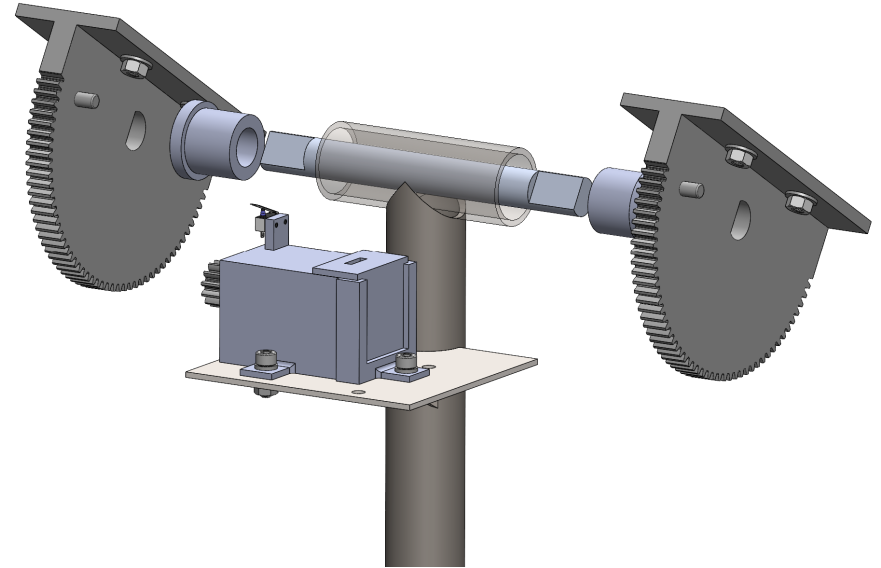


$$T_{applied} = \left( \frac{96 \text{ teeth}}{12 \text{ teeth}} \right) * 13 \text{ lb} \cdot \text{in} = 104 \text{ lb} \cdot \text{in}$$

# Motion

## Key Feature: Interchangeable Gears

- Injection molded Nylon
- Low speed = Low wear
- Identical parts for maintenance and cost



# Motion

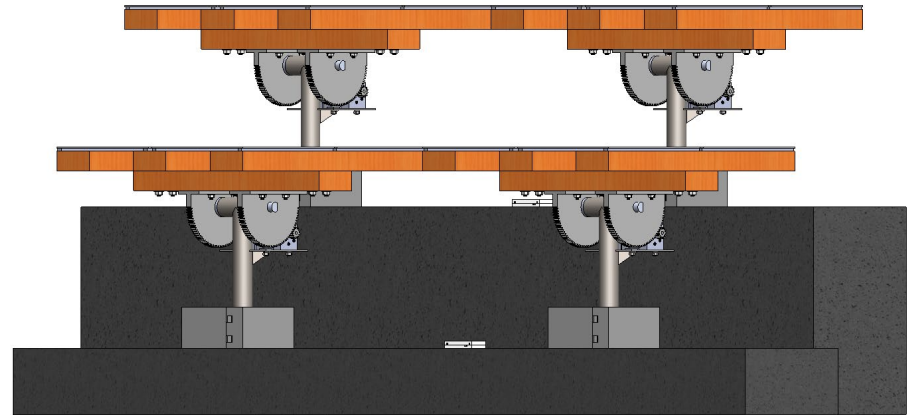
## Key Feature: High Wind Safety Mode

- Triggered at **40 mph** wind speed
- Staggered defense mode

$$W_{module} = 15 \text{ lbs}$$

$$F_{lift} = \frac{1}{2} \rho v^2 A \sin \theta C_L$$

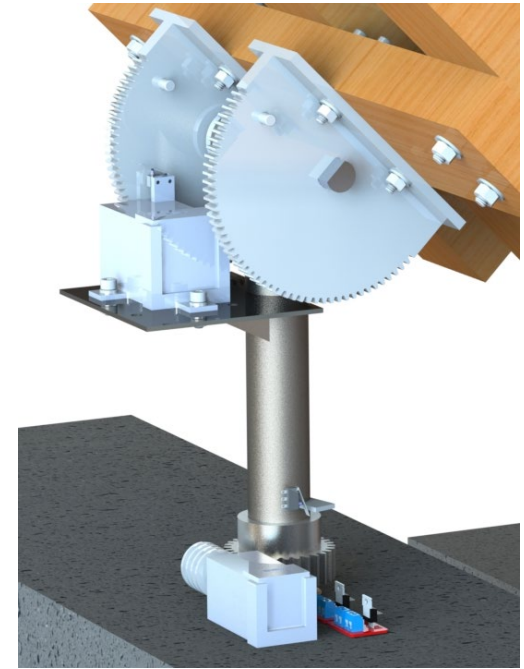
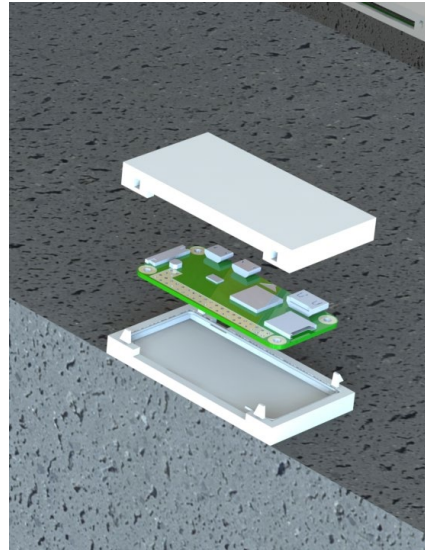
$$V = \sqrt{\frac{2W_{module}}{\rho A \sin \theta C_L}} = 40 \text{ mph}$$



# Electronics

Customer Needs Addressed: 8, 9, 11, 12

- Uses a Raspberry Pi 0W for control
- Manages two heliostats
- Control of both axes

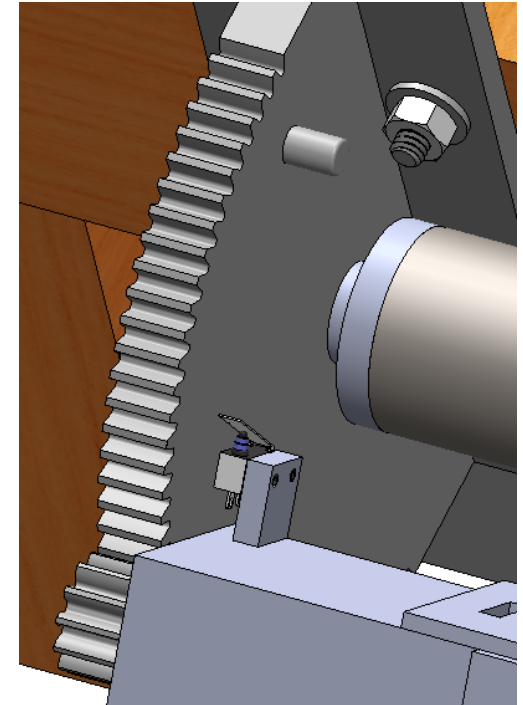
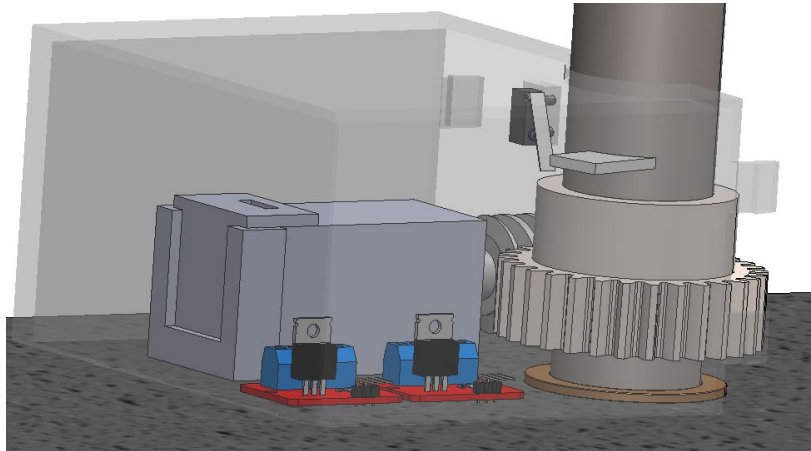




# Electronics

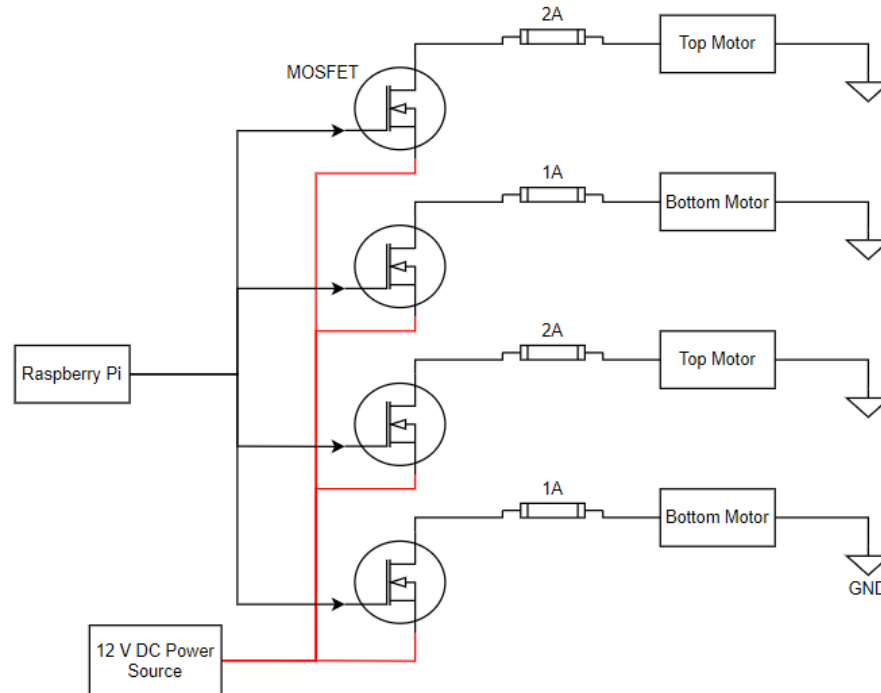
## Key Feature: Switches and Drivers

- Uses Omron Long Lever Switches
- IRF520 MOSFET as motor driver
- 2A and 1A fuses for overcurrent



# Electronics

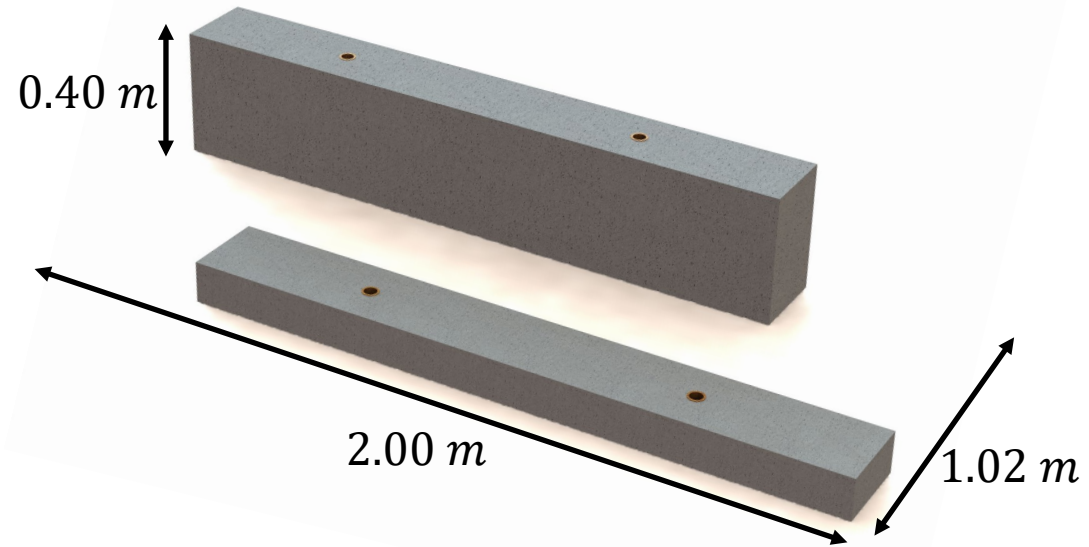
## Key Feature: Power Diagram



# Structure

Customer Needs Addressed: 2, 3, 6, 7, 10, 15

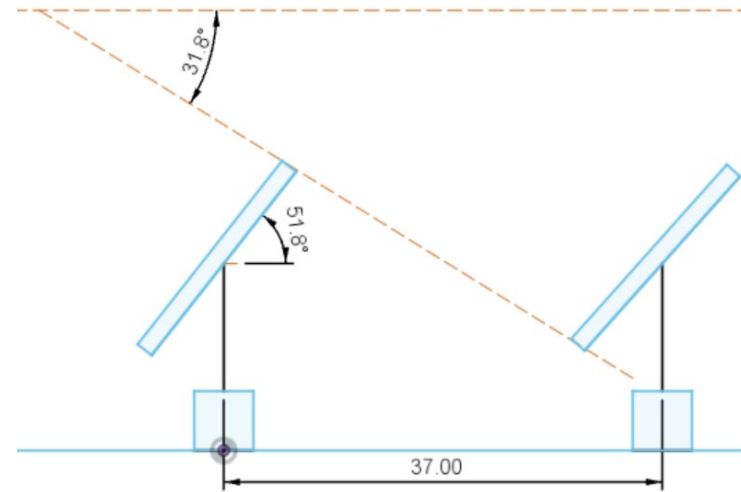
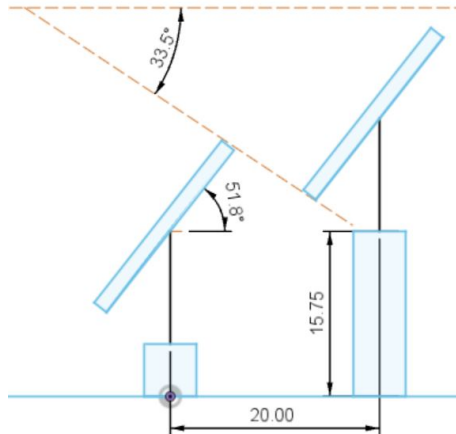
- $2.04 \text{ m}^2$  footprint
- Durable and Cheap



# Structure

## Key Feature: Shading Removal

- Winter Solstice
  - $33.5^\circ$  Solar noon elevation



- Summer Solstice
  - $77^\circ$  Solar noon elevation
  - Collection Period: 8:15 AM– 5:15 PM

# Structure

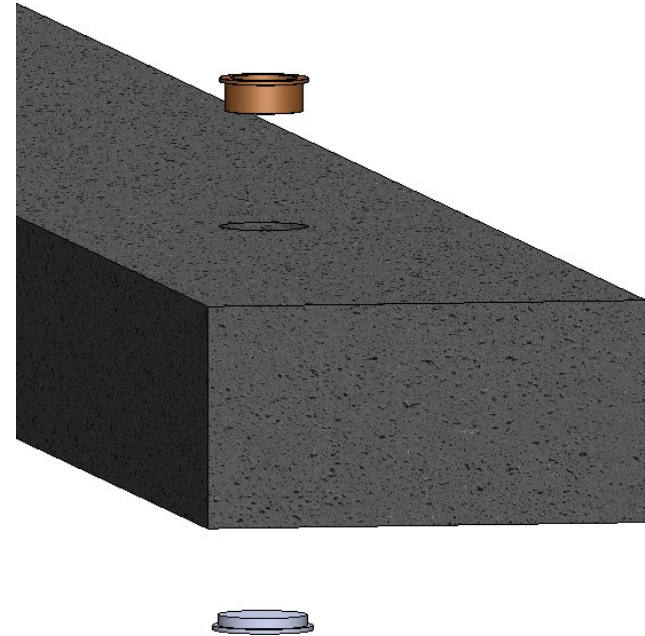
## Key Feature: Furniture Sliders

- Low friction support

$$\mu = 0.20$$

- Bronze bushings

$$\mu = 0.16$$



# Cleaning and Maintenance Procedure

- Apply wood sealer every 2 years
- Compressed air every 2 weeks
- Water pressure with detergent if necessary



From: *Raising the Lifetime of Functional Materials for Concentrated Solar Power Technology*

# Cost Summary

## Raw Materials<sup>1</sup> (\$129.09)

- Structural components
- Reflective surface

## OTS Parts<sup>1</sup> (\$171.87)

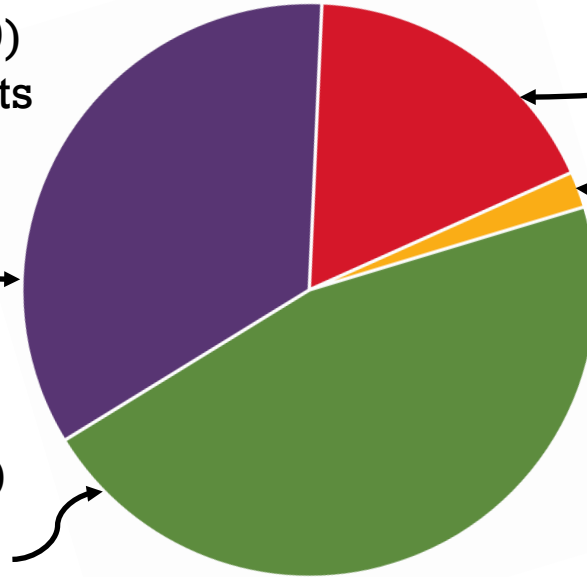
- Electronics
- Actuators
- Hardware

## Manufacturing (\$65.89)

- Raw material manipulation
- Injection molding

## Assembly (\$7.62)

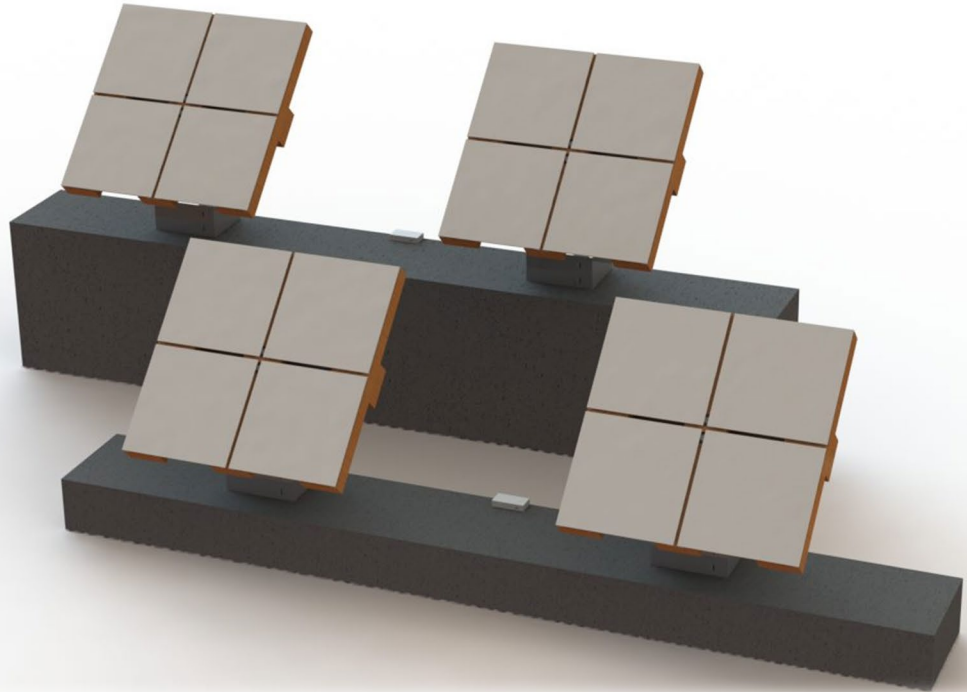
- Handling time



<sup>1</sup>Some costs considered are for prototyping only. As more accurate quotes are obtained from suppliers, the overall cost is expected to decrease.

# Why Us?

- Fully operational
  - Robust, reliable
- No cutting corners





# Thank you!

■ Questions?

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The background is a dense, semi-transparent collage of various images showing students and faculty members in engineering settings, such as classrooms, labs, and meetings. The collage is overlaid on a solid blue background. A vertical orange bar is positioned on the far left side of the image.

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# Reflective Surface

## Thermal Input Calculations

Solar Radiation striking Earth's surface:

$$G_{bn} = G_{on} \tau_b$$

$$G_{on} = G_{sc} \left( 1 + 0.033 \cos \left( \frac{360n}{365} \right) \right)$$

$$\tau_b = a_0 + a_1 e^{\left( -\frac{k}{\cos \theta_z} \right)}$$

$$a_0 = 0.4237 - 0.00821(6 - A)^2$$

$$a_1 = 0.5055 - 0.00595(6.5 - A)^2$$

$$k = 0.2711 - 0.01858(2.5 - A)^2$$

$$Q = G_{bt} A \eta_{opt}$$

$$\eta_{opt} = 0.5 \eta_{ref}$$

$$G_{bt} = G_{bn} \cos \theta_{inc}$$

Angle of Incidence:

$$\cos(2\theta_{inc}) = \bar{S} \cdot \bar{H}$$

$$\bar{S} = \cos \alpha_s \sin \gamma_s \hat{i} - \cos \alpha_s \cos \gamma_s \hat{j} + \sin \alpha_s \hat{k}$$

$$\bar{H} = \cos \alpha_t \sin \gamma_t \hat{i} - \cos \alpha_t \cos \gamma_t \hat{j} + \sin \alpha_t \hat{k}$$

The sun is assumed to be at solar noon during the winter solstice to replicate the worst day of the year for thermal collection.

# Reflective Surface

## Solar Concentration Calculation

$$Q = q_{solar} A_{receiver}$$

$$A_{receiver} = \frac{Q}{q_{solar}} = 1m^2$$

$$q_{solar} = G_{bn} C_{geo} \eta_{opt}$$

$$C_{geo} = \frac{A_{heliostats}}{A_{receiver}}$$

$$q_{solar} = 1,635 \text{ suns}$$

# Reflective Backing

## Composite Cantilever Beam Deflection Calculation

$$F = \frac{E_{glass}}{E_{cedar}} = 12.73$$

$$I = \sum I_i + A_i d_i^2$$

$$\delta = \frac{FL^3}{3EI}$$

$$\sigma_{max} = F \frac{Mc}{I}$$

$$FOS = \frac{\sigma_{glassyield}}{\sigma_{max}}$$

