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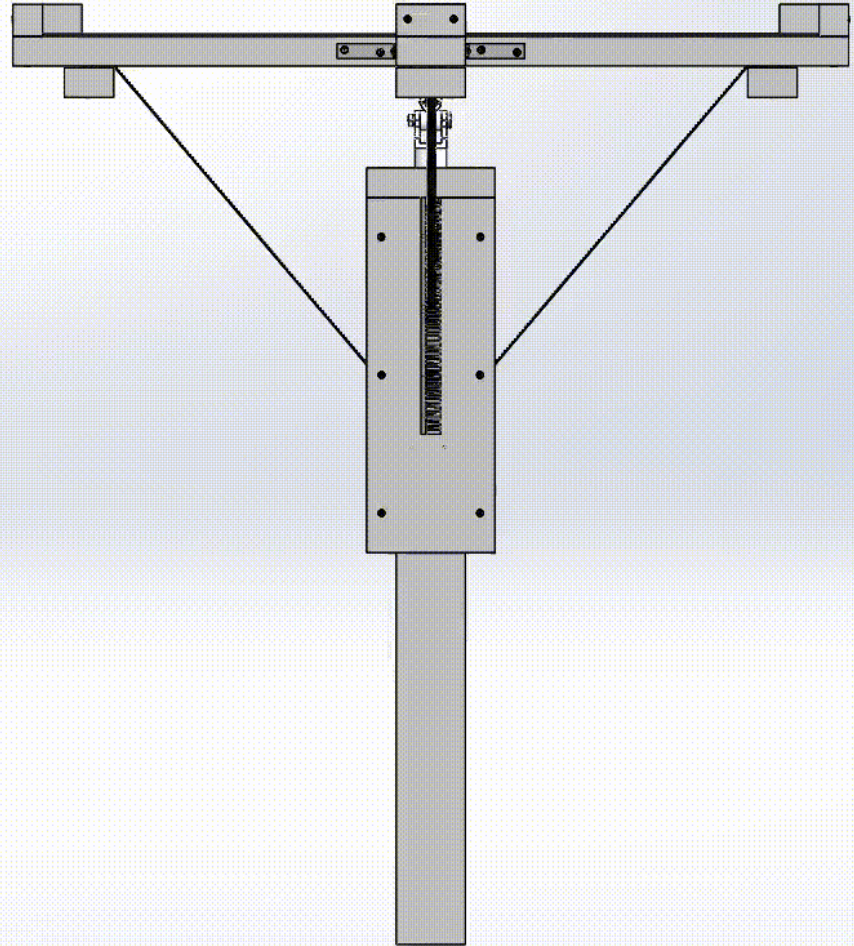
Illumigator

Small-Scale Heliostat for Industrial Solar Processing

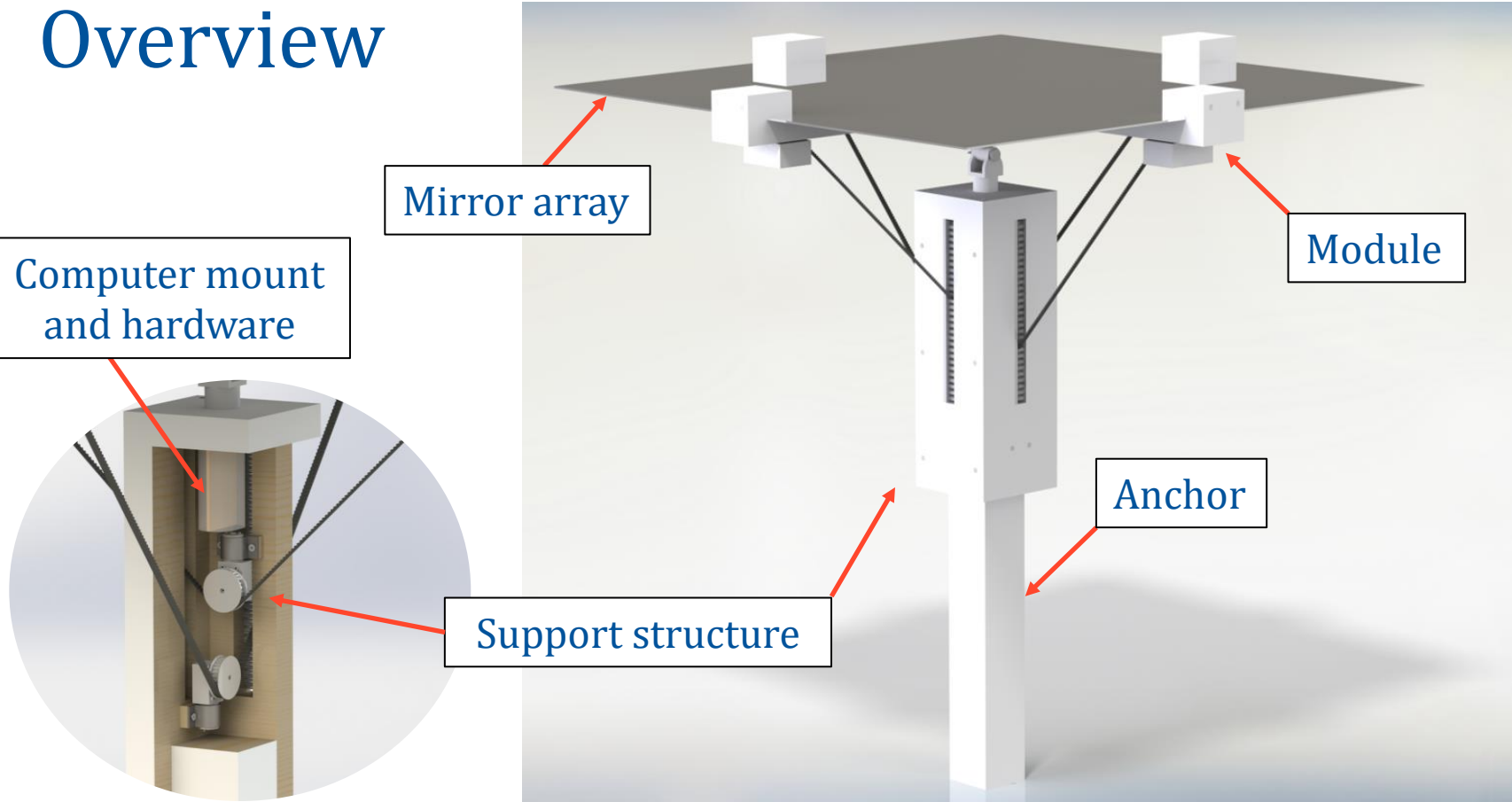
Section 1355, Group 5

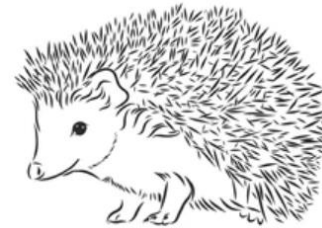
Bryce Behm, Christopher Boor, Daniel DeCario, Alfredo Delgado, Ethan Haddorff, Jacob McKishnie, Kiran Mital, Spencer Steinmetz

The Illumigator



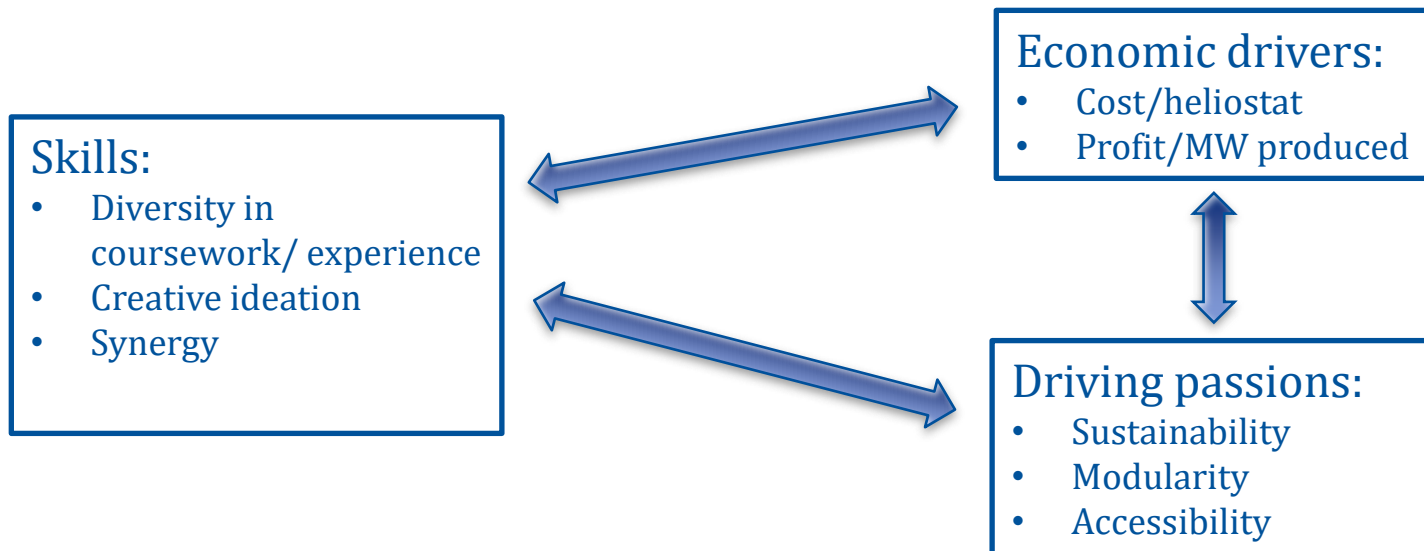
Overview



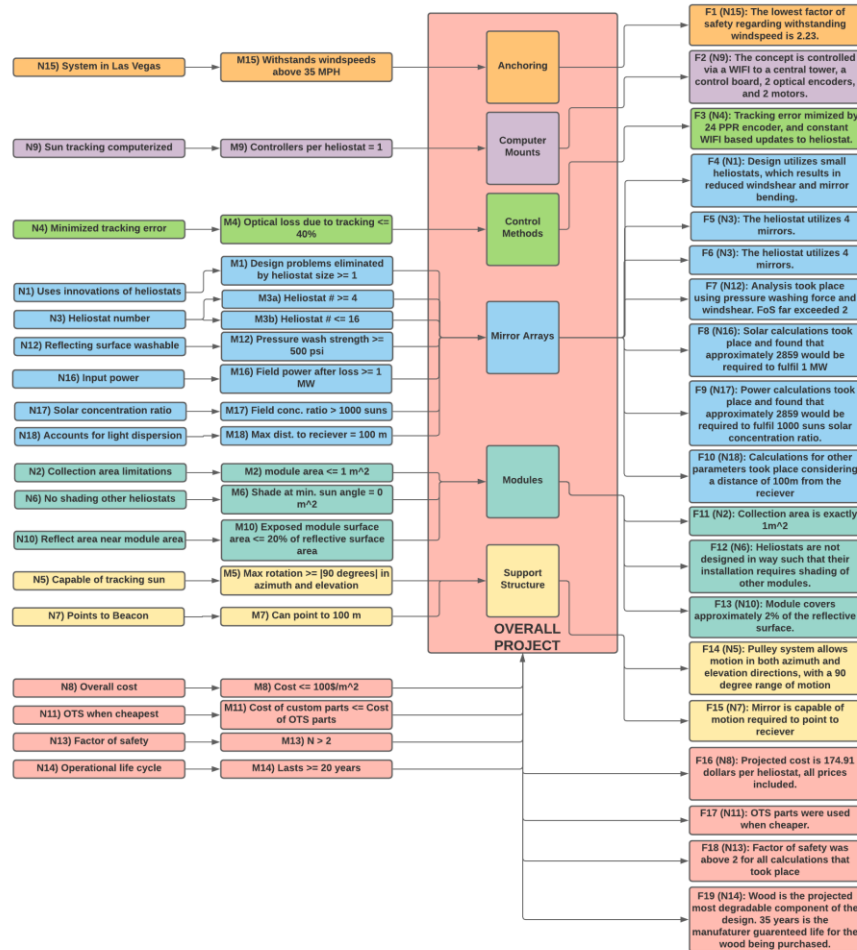


Core Value Proposition

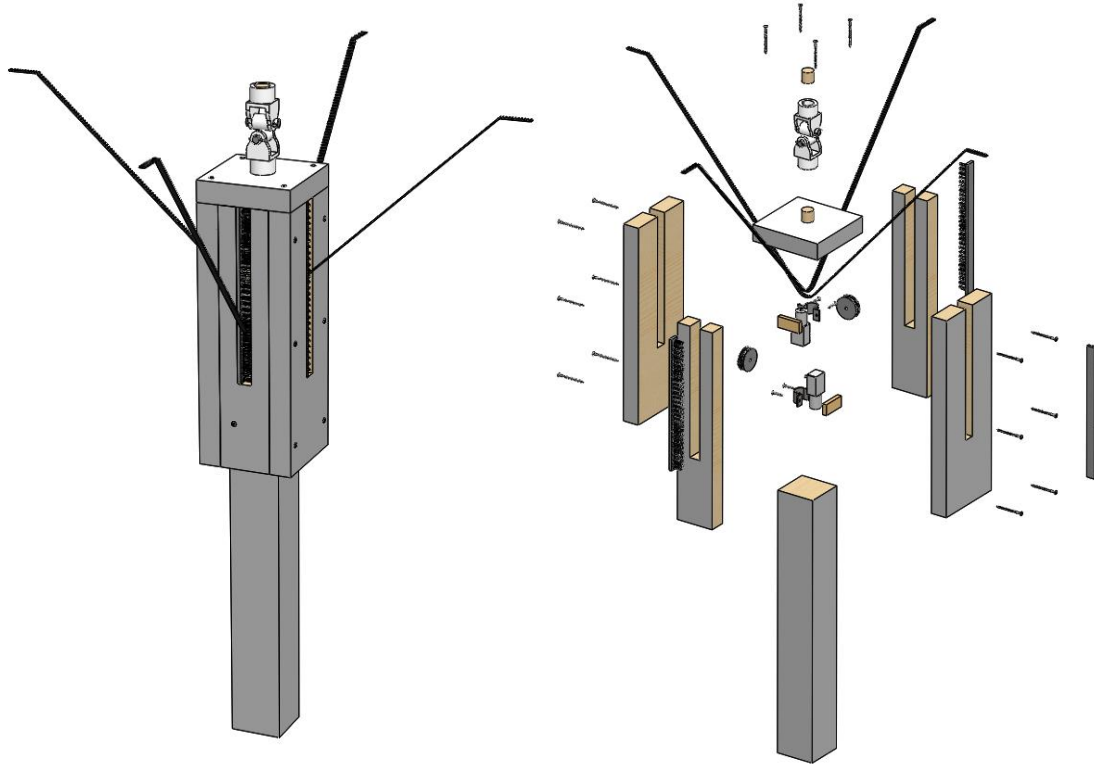
Our “Hedgehog Concept”



Customer Needs Map



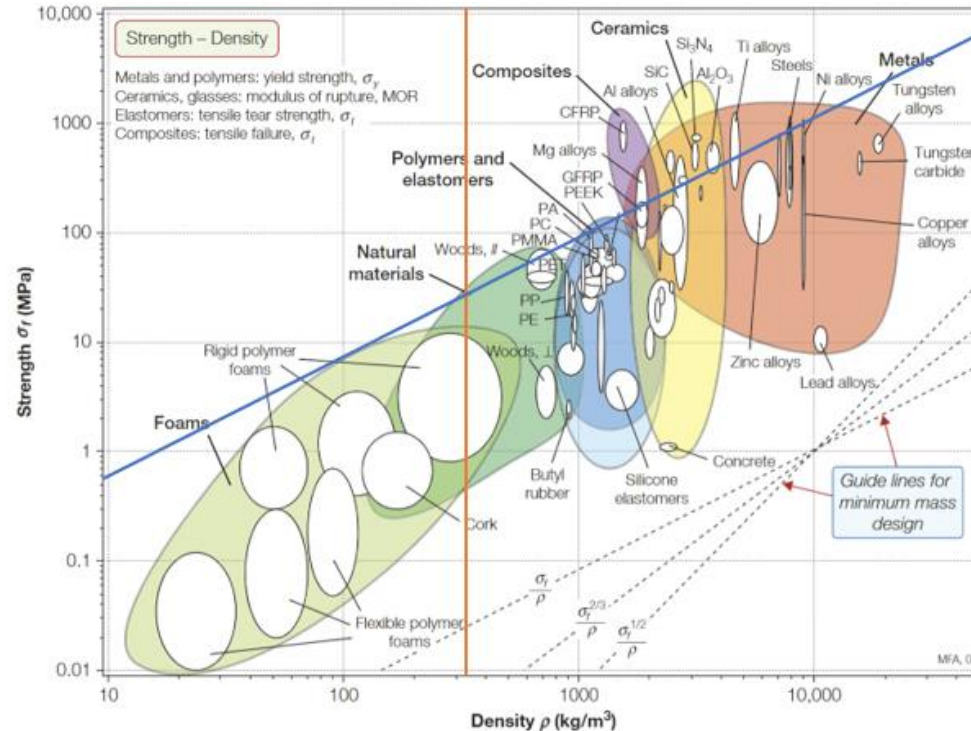
Subsystem 1+2: Support Structure/Anchor



- Primary material = pressure-treated pine wood
- 3D-printed universal joint and timing belt pulleys for module actuation
- Painted to protect from corrosion and limit interior temperature changes

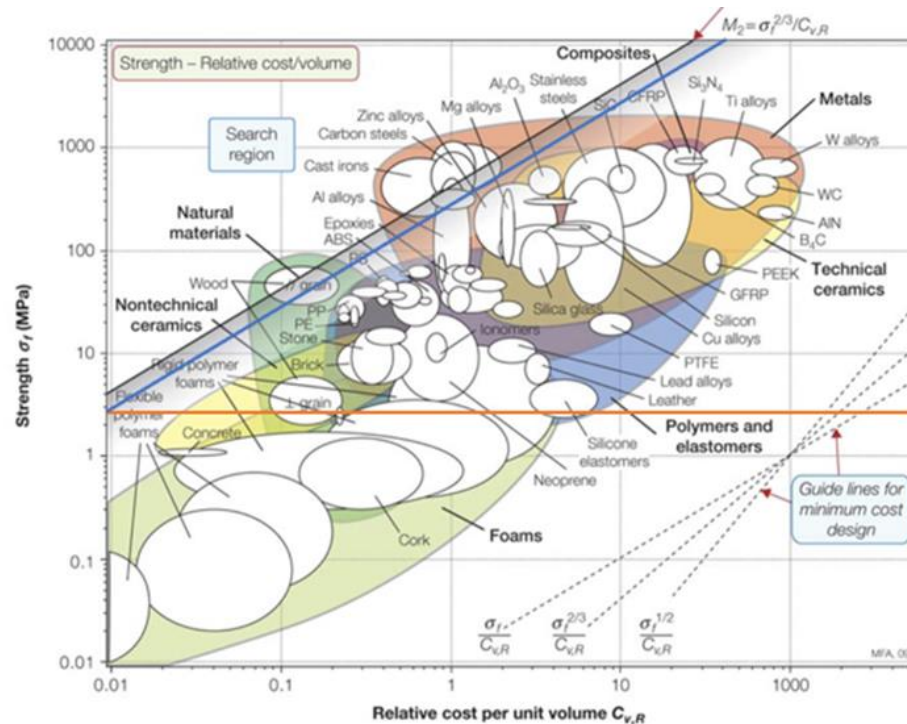
Support Structure/Anchor Material Selection

- Low Cost and density
- Modular
- >20-year lifetime
- Ashby analysis



Support Structure/Anchor Material Selection

- Low Cost and density
- Modular
- >20-year lifetime
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Support Structure Analysis: U-joint

$$\sigma_{y,1} = \frac{P}{A} = \frac{105 \text{ N}}{0.00051 \text{ m}^2} = 205.9 \text{ kPa}$$

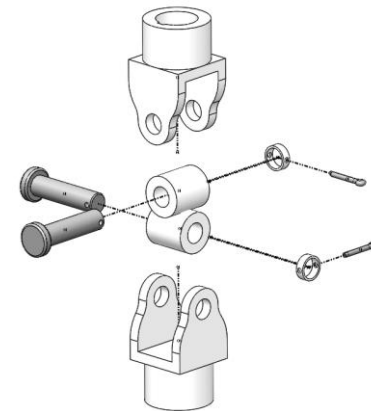
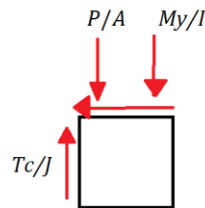
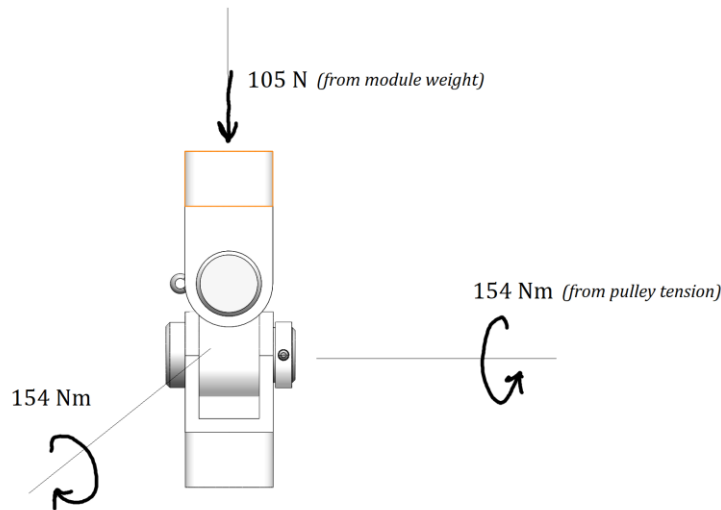
$$\sigma_{y,2} = \frac{My}{I} = \frac{154 \text{ N} * \left(\frac{.0254 \text{ m}}{2}\right)}{\frac{\pi}{64} * .0254 \text{ m}^4} = 97.79 \text{ MPa}$$

$$\tau = \frac{Tc}{J} = \frac{154 \text{ N} * \left(\frac{.0254 \text{ m}}{2}\right)}{\frac{\pi}{32} * .0254 \text{ m}^4} = 47.86 \text{ MPa}$$

$$\text{center} = \frac{98 \text{ MPa}}{2} = 49 \text{ MPa}$$

$$\text{radius} = (47.86^2 + 98^2)^{\frac{1}{2}} = 109.06 \text{ MPa}$$

$$\sigma_a = 158.06 \text{ MPa}, \quad \sigma_b = -60.6 \text{ MPa}$$



Brittle Failure Criteria

1004 steel UTS= 565 MPa

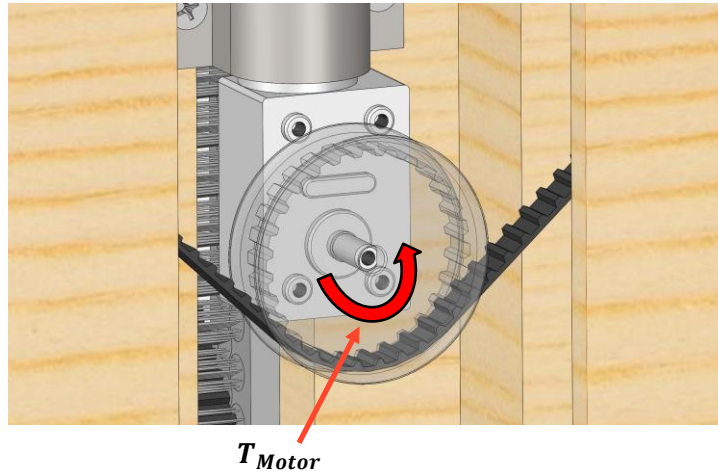
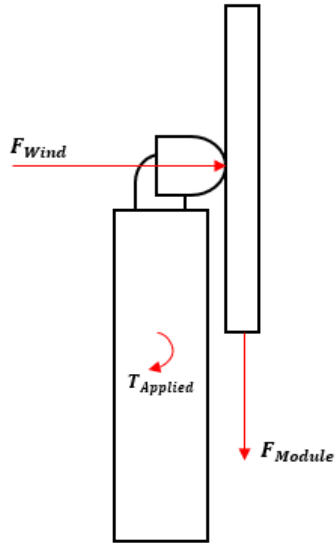
Max normal stress criterion:

$$n_1 = \frac{565}{158.06} = 3.57, \quad n_2 = \frac{565}{60.6} = 9.32$$

Coulomb-Mohr criterion:

$$n = \left(\frac{158.06 + 60.6}{565} \right)^{-1} = 2.58$$

Support Structure Analysis: Minimum Factor of Safety



Material mass and volume:

$$M_w = \rho_w * V_w$$

$$V_w = l * w * h$$

$$V_{w1} = 0.0889 * 0.0381 * 1.076 = 0.00364 \text{ m}^3$$

$$V_{w2} = 0.0889 * 0.041275 * 0.0381 = 0.000140 \text{ m}^3$$

$$V_{w3} = 0.0889 * 0.0381 * 0.0508 = 0.000172 \text{ m}^3$$

$$M_w = 350 \frac{\text{kg}}{\text{m}^3} * 1.1649 \text{ m}^3 = 2.985 \text{ kg}$$

$$M_g = \rho_g * V_g = 2200 \frac{\text{kg}}{\text{m}^3} * 1 \text{ m}^2 * 0.003175 \text{ m} = 6.985 \text{ kg}$$

$$M_{total} = M_g + M_w = 9.97 \text{ kg} \Rightarrow F_{mod} = 97.8 \text{ N}$$

Applied force and torque:

$$F_{wind} = A * P * C_d$$

$$P = 0.613V^2 = 0.613 * 15.65^2 = 150.14 \text{ N/m}^2$$

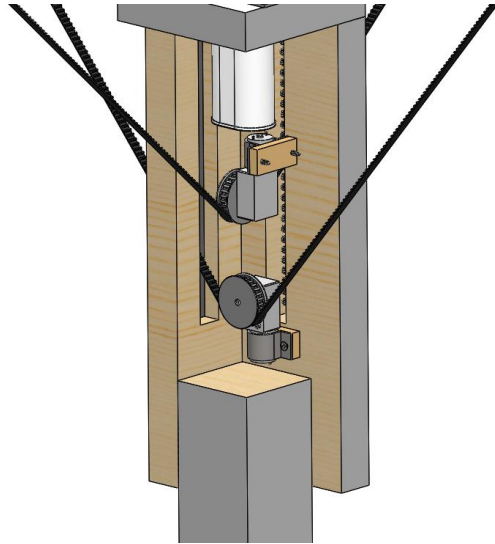
$$F_{wind} = 1 * 150.14 * 1.4 = 210.19 \text{ N}$$

$$\Rightarrow F_{total} = F_{wind} + F_{mod} = 308 \text{ N}$$

$$T_{applied} = F_{total} * \frac{D}{2} = 308 * \frac{0.044602}{2} = 6.87 \text{ N} * \text{m}$$

$$N = \frac{T_{stall}}{T_{applied}} = \frac{44.145}{6.87} = 6.43$$

Support Structure Analysis: Motor Lifetime

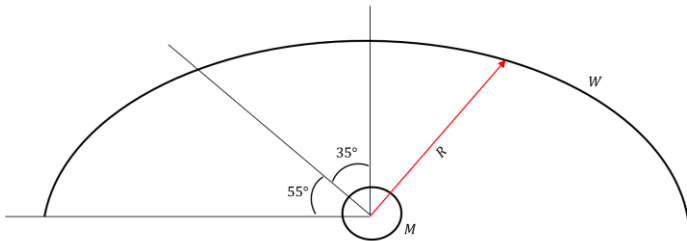


- Dual motors for azimuth and elevation angles

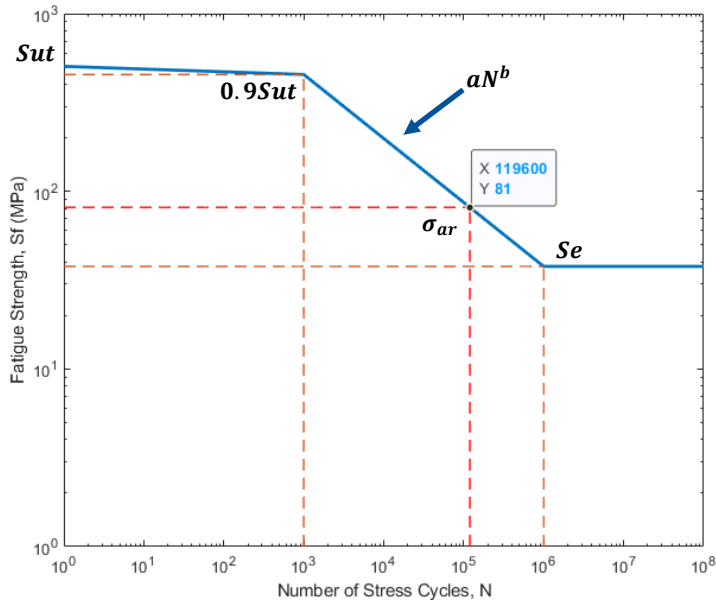
- $$\frac{\text{Cycles}}{\text{day}} = \frac{\text{Arc length } W}{\text{Circumference } M} = \frac{R\theta}{\pi D}$$

- Top motor: $\frac{0.4569 \text{ m}}{0.165 \text{ m}} * 2 \sim \frac{6 \text{ cycles}}{\text{day}} = 43,800 \text{ cycles at 20 years}$

- Bottom motor: $\frac{0.5210 \text{ m}}{0.165 \text{ m}} * 2 \sim \frac{7 \text{ cycles}}{\text{day}} = 51,100 \text{ cycles at 20 years}$



Support Structure Analysis: Motor Lifetime



- $\sigma_{ar} = aN^b \Rightarrow N = \left(\frac{\sigma_{ar}}{a}\right)^{\frac{1}{b}}$
- $a = \frac{(0.9S_{ut})^2}{S_e} = \frac{(0.9 \cdot 505)^2}{37.8} = 5470.8$
- $b = \frac{-1}{3} \log\left(\frac{0.9S_{ut}}{S_e}\right) = \frac{-1}{3} \log\left(\frac{0.9 \cdot 505}{37.8}\right) = -0.360$
- $S_e = k_a k_b k_c k_d k_e k_f * 0.5S_{ut} = .807(.997)(.590)(1.00)(.814)(.387) * 252.5$

k_a = Surface factor

k_a = Size factor

k_a = Loading factor

k_a = Temperature factor

k_a = Reliability factor

k_f = Miscellaneous factors (plating, surface imperfections, fretting, etc.)

- $\tau = \frac{Tc}{J} = \frac{6.87(.003)}{(1.27 \cdot 10^{-10})} = 162.283 \Rightarrow \sigma_{ar} = \frac{162.283 \cdot 0}{2} = 81.142 \text{ MPa}$
- $N = \left(\frac{81.142}{5470.8}\right)^{\frac{-1}{0.360}} = 119,560 \text{ cycles}$

Support Structure Analysis: Interior Heat Transfer

1. Ambient air:

$$Re = \frac{ux}{\nu}$$

$$Nu = 0.332(Re)^{\frac{1}{2}}(Pr)^{\frac{1}{3}}$$

$$u = 15.6 \text{ m/s}, T_{\infty} = 320.8 \text{ K}$$

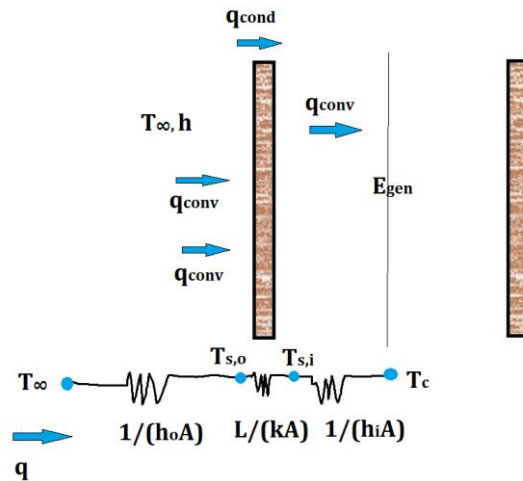
$$\rightarrow T_{s,o} = 317.3 \text{ K}, T_{s,i} = 298.6 \text{ K}$$

Operating temperatures:

- Motor: -30 to 70°C
- Controller: -40 - 85°C

$$P = VI \triangleq q = 58.9 \text{ W}$$

$$qR = T_i - T_j$$



2. Iterative process to determine T_c

Guess T_c

$$Ra = \frac{g\beta(T_c - T_{s,i})D^3}{\nu\alpha}$$

$$\overline{Nu}_L = 0.68 + \frac{0.67Ra^{\frac{1}{4}}}{\left(1 + \left(\frac{0.492}{Pr}\right)^{\frac{9}{16}}\right)^{\frac{4}{9}}} = \frac{hL}{k}$$

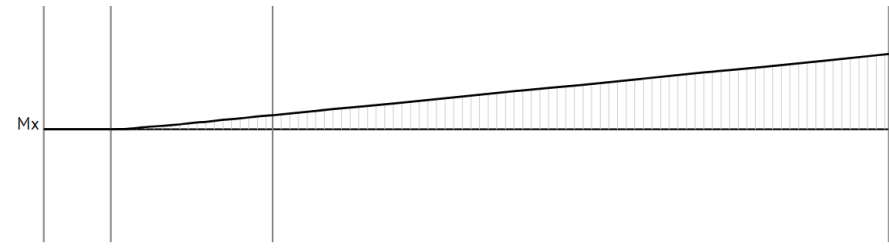
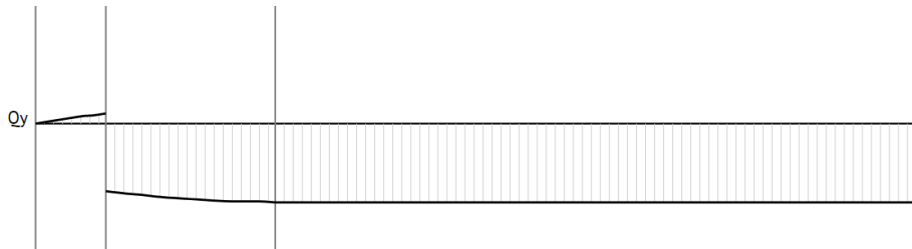
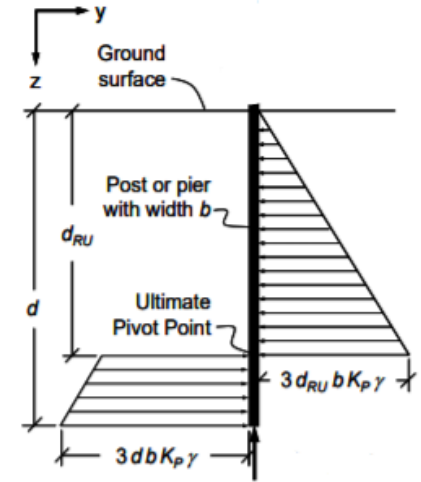
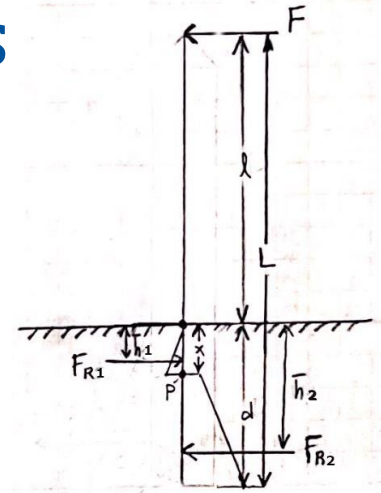
$$q = h(T_c - T_{s,i})$$

$$\rightarrow T_c = 310.6 \text{ K} = 37.45^\circ\text{C}$$

Anchor Analysis: Statics

- d = depth = 0.3048 m
- d_{RU} = pivot depth = 0.2155 m
- B = post width = 0.1016 m
- K_p = coefficient of passive earth pressure = 3.690
- γ = moist unit weight = 16677 N/m³

- $$F_{max} = \frac{K_p \gamma w d^3}{3(l+x)} = 170.83 \text{ N}$$



Customer Needs: Support Structure

5. Dual-axis solar tracking

7. Can point to receiver 100 m away

11. Utilizes OTS parts, and custom parts when cheaper

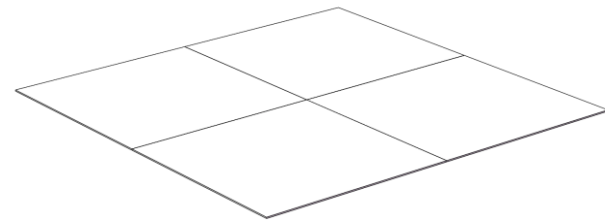
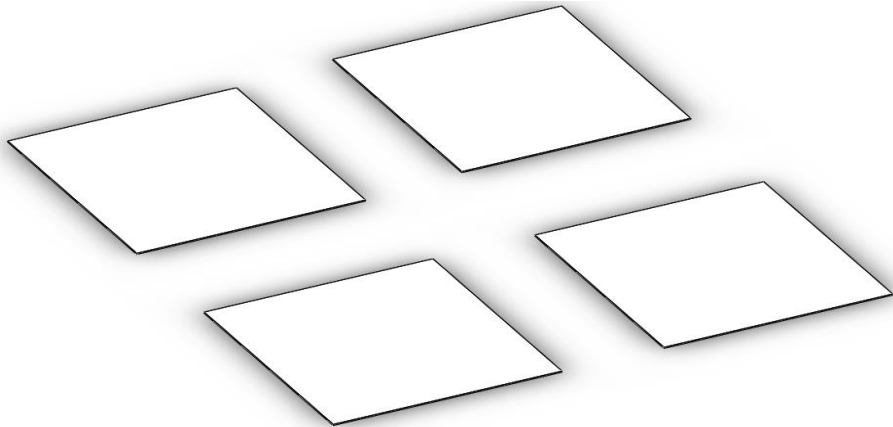
13. High factor of safety

14. High operational lifetime

Customer Needs: Anchor

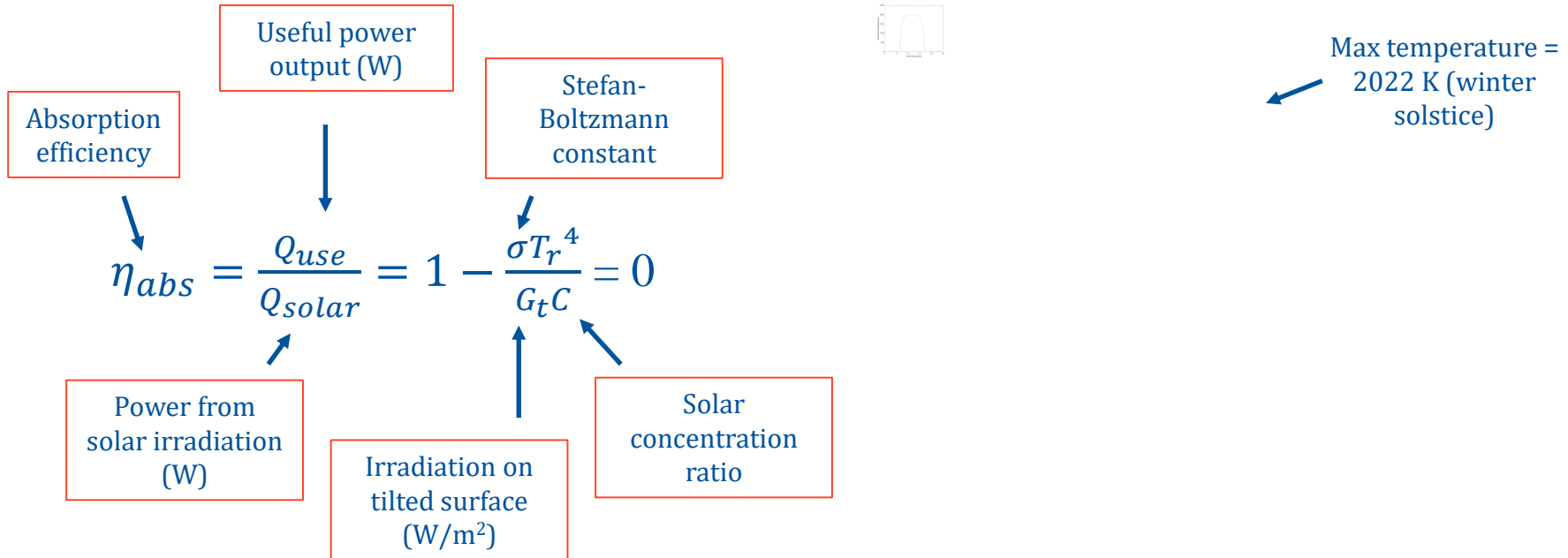
15. Allows heliostat to withstand Las Vegas wind speeds

Subsystem 3: Mirror Array

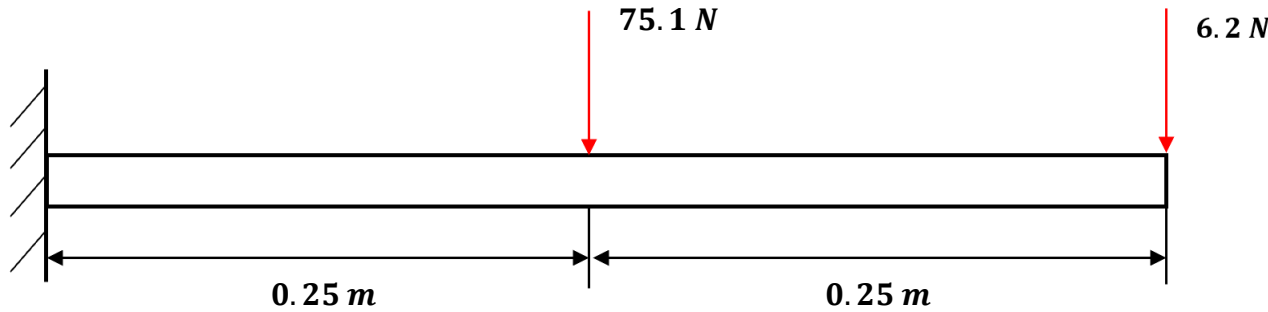


- 4 total OTS mirrors per heliostat
- Minimal tracking error
- Customer needs addressed:
- Lift force of 33.756 lbs from maximum wind speed of 35 *mph*

Mirror Array Analysis: Maximum Receiver Temperature



Mirror Array Analysis: Wind Shear and Cleaning



- $P * \frac{A}{2} = 150.14 \frac{N}{m^2} * 0.5 m^2 = 75.1 N$

- $A = \pi r^2 = \pi(0.762)^2 = 1.824 mm^2$

- $F = \sigma A = 3.4 MPa * 1.824 mm^2 = 6.20 N$

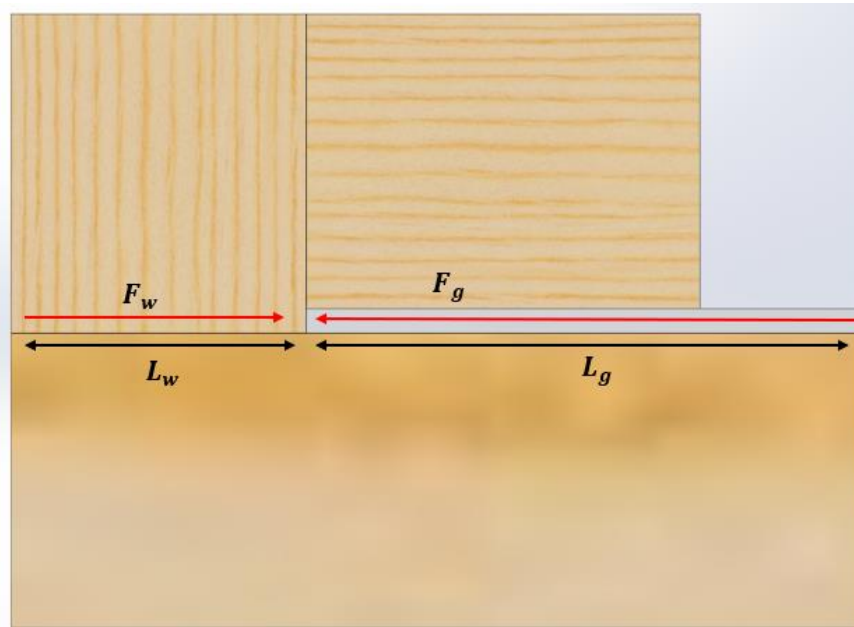
- $\sigma_1 = \frac{6FL}{bh^2} = \frac{6(75.1)(0.25)}{(0.0889)(0.0413)^2} = 0.743 MPa$

- $\sigma_2 = \frac{6FL}{bh^2} = \frac{6(6.2)(0.25)}{(0.0889)(0.0413)^2} = 0.0613 MPa$

- $\sigma_{total} = \sigma_1 + \sigma_2 = 0.8043 MPa$

- $N_{mod} = \frac{2.31}{0.8043} = 2.87, \sigma_{total} \ll S_{ut\ glass} = 1000 MPa$

Mirror Array Analysis: Thermal Expansion



Glass:

$$\alpha_g = 0.55 * 10^{-6} / ^\circ C$$

$$\Delta T = +13 ^\circ C$$

$$\Delta l = \alpha_g L_g \Delta T = (0.55 * 10^{-6} / ^\circ C)(0.5)(13) = 3.575 * 10^{-6} \text{ m}$$

$$\varepsilon = \frac{\Delta l}{l_0} = \frac{3.575 * 10^{-6}}{0.5} = 7.15 \mu m$$

$$\sigma_{dt} = E_{glass} \varepsilon = 74.8 \text{ GPa} * 7.15 \mu m = \mathbf{534.82 \text{ kPa}}$$

Wood:

$$\alpha_w = 0.58 * 10^{-6} / ^\circ C$$

$$\Delta T = +13 ^\circ C$$

$$\Delta l = \alpha_w L_w \Delta T = (0.58 * 10^{-6} / ^\circ C)(0.0381)(13) = 2.873 * 10^{-6} \text{ m}$$

$$\varepsilon = \frac{\Delta l}{l_0} = \frac{0.2873 \mu m}{0.0381 \text{ m}} = 7.53 \mu m$$

$$\sigma_{dt} = E_{wood} \varepsilon = 10 \text{ GPa} * 7.53 \mu m = \mathbf{75.3 \text{ kPa}}$$

Customer Needs: Mirror Array

1. Area = 1 m^2

3. Each module must be composed of 4-16 heliostats

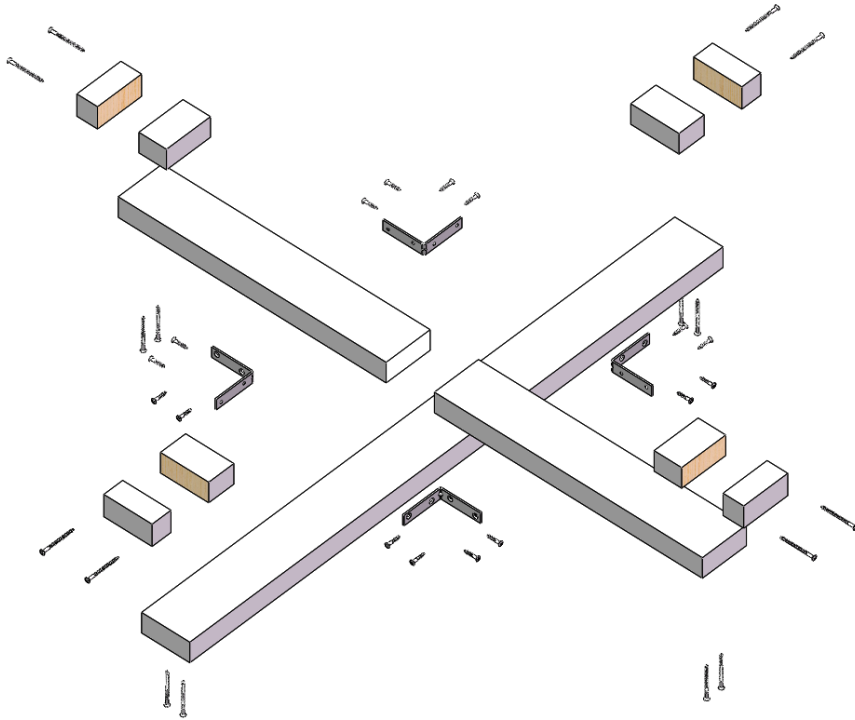
12. Reflecting surface must be washable

16. Focal thermal input power of 1 MW after losses

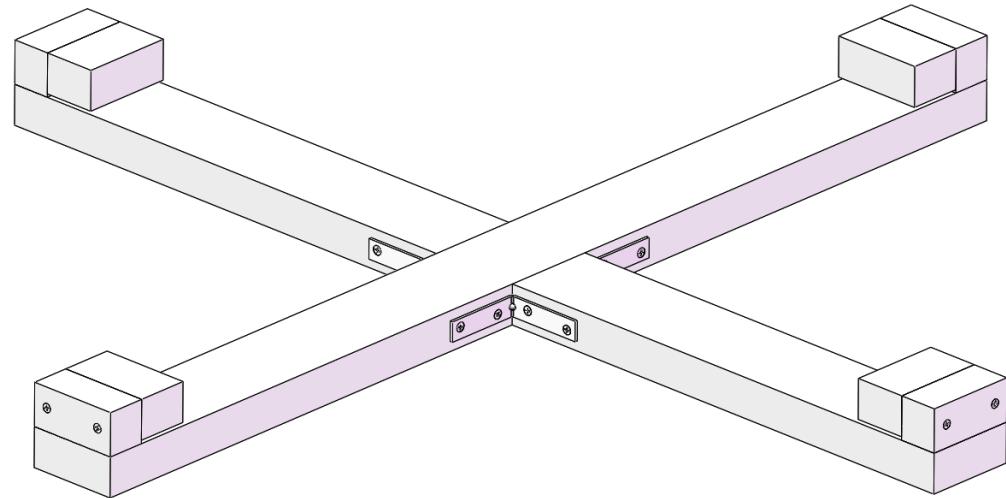
17. Solar concentration ratio is greater than 1000 suns

18. Accounts for light dispersion

Subsystem 4: Module



- Primary material = wood
- Lightweight, capable of dual-axis solar tracking
- Clamps to secure mirrors



Module Analysis: Shading Between Units

Determining Reflective Area

$$A_{rec} = \frac{Q}{q} = \frac{\text{power input}}{\text{solar flux}}$$

$$\frac{A_{\text{heliostats}}}{A_{rec}} = C = 1000$$

→ 2859 heliostats of 1 m^2 area

Shading Between Mirrors

0.018 m^2 shaded by clamps

→ **2913** heliostats of 1 m^2 area, or decreased receiver size

Shading Between Heliostats

$$\text{field size} = \frac{1}{2} * [\pi(100 \text{ m})^2] = 15708 \text{ m}^2$$

$$\frac{15708 \text{ m}^2}{2913 \text{ heliostats}} = 5.4 \text{ m}^2 \text{ per unit}$$

→ Sufficient spacing, no shading in field

Module Analysis: Lift Force

The following formula defines the wind pressure on the heliostat module:

$$P = 0.00256 * v^2$$

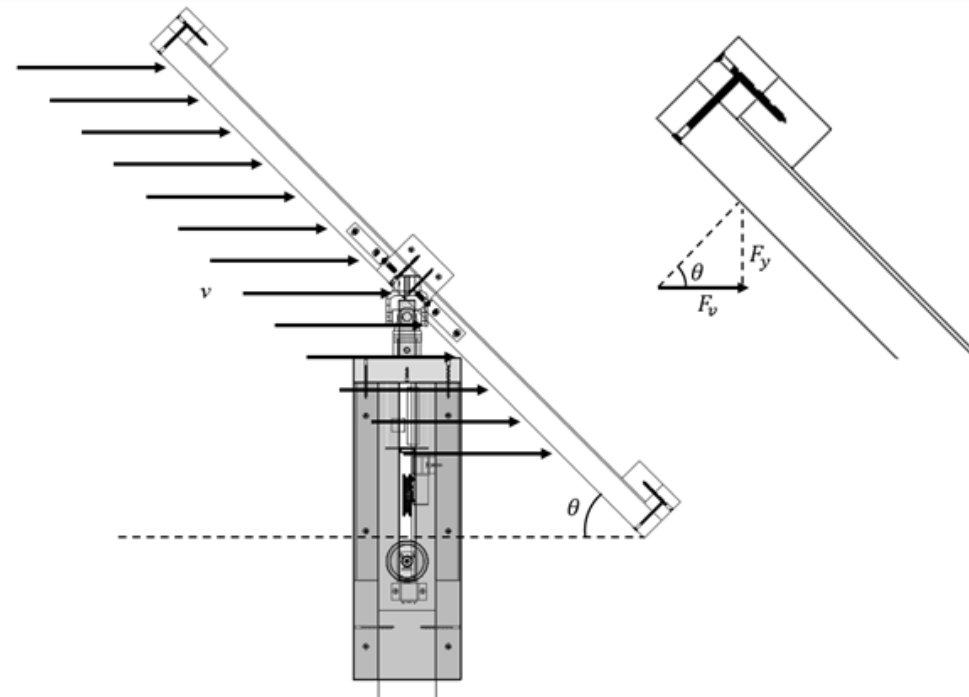
$$P = \frac{F}{A}$$

Vertical Lift Force:

$$F_y = 0.00256 * v^2 * A * \tan(\theta)$$

Assuming an angle of 45° , a wind speed of 35 mph , and a module area of 1 m^2 or 10.7639 ft^2 , the vertical force is then:

$$\begin{aligned} F_y &= 0.00256 * (35 \text{ mph})^2 * (10.7639 \text{ ft}^2) * \tan(45^\circ) \\ &= \mathbf{33.756 \text{ lbs}} \end{aligned}$$



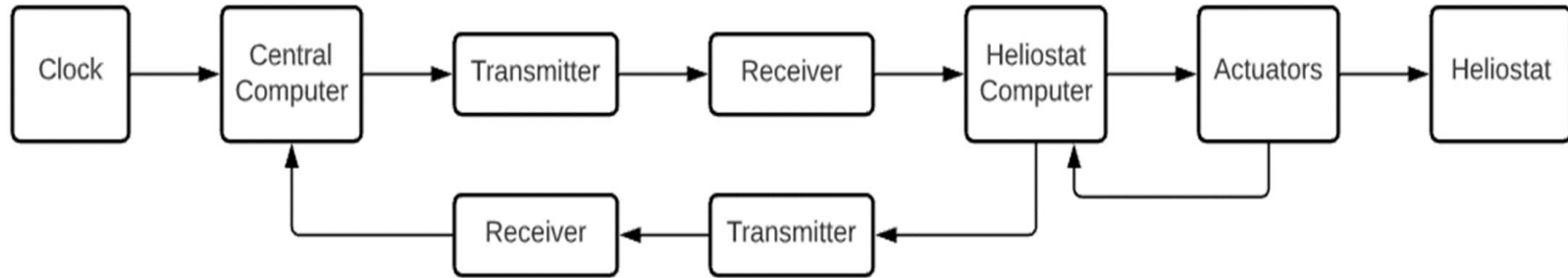
Customer Needs: Module

2. No mirror shading within heliostat

6. No shading between heliostats

10. Exposed module area $< 20\%$ reflective area

Subsystem 5: Control System



- Feedback control with inputted solar data
- Receives information from central computer
- Continual closed loop system between actuators and heliostat ensures long-lasting accuracy

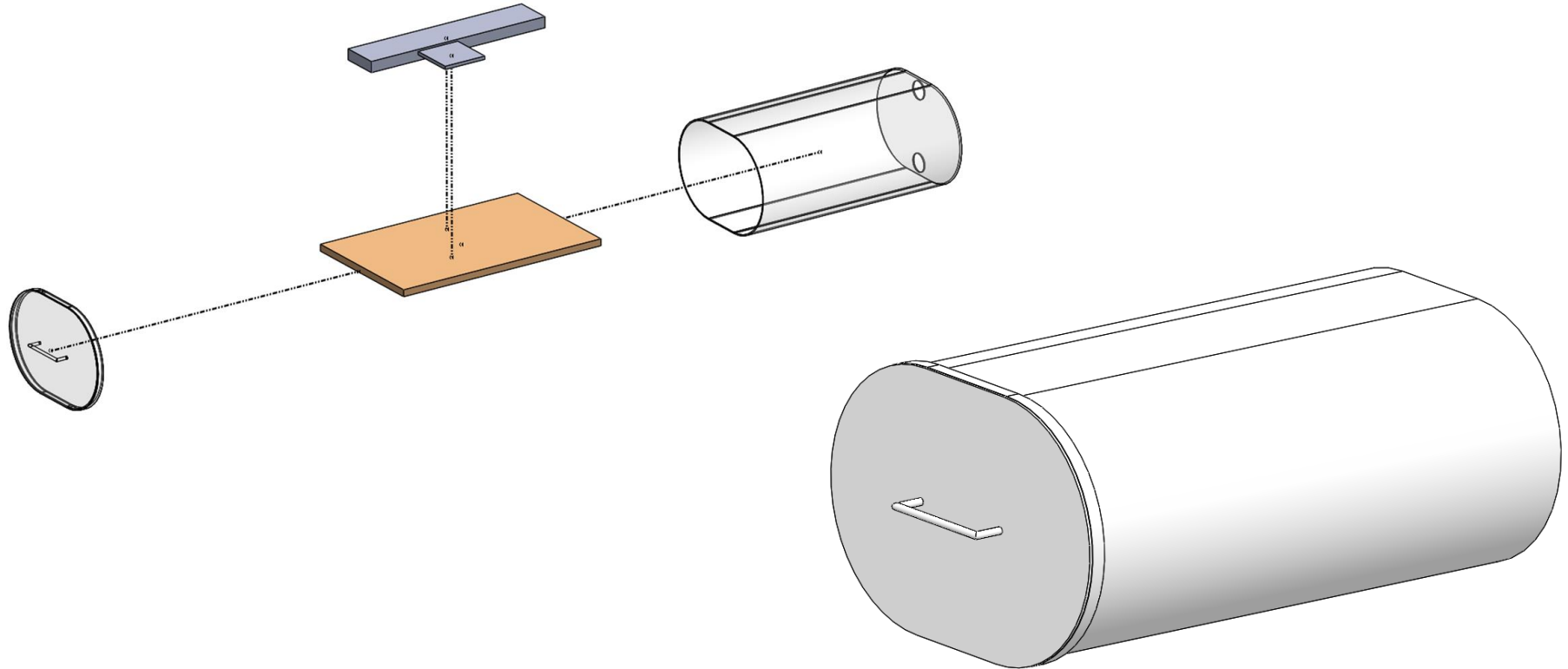
Customer Needs: Control System

4. Encoder allows for minimal tracking error

5. Built-in dual-axis solar tracking

14. Feedback control = high operational lifetime

Subsystem 6: Hardware Mount



Customer Needs: Hardware Mount

9. Allows for computerized tracking via central computer

11. Utilizes OTS parts, besides custom mounting platform

Unique Features

- Painted Pressure-Treated Wood
- Pulley Belt System
- Internally mounted components

Material Cost Table: Subsystem Breakdown

Mirror array:

~\$21.48

(4 mirrors, per manufacturer quote)

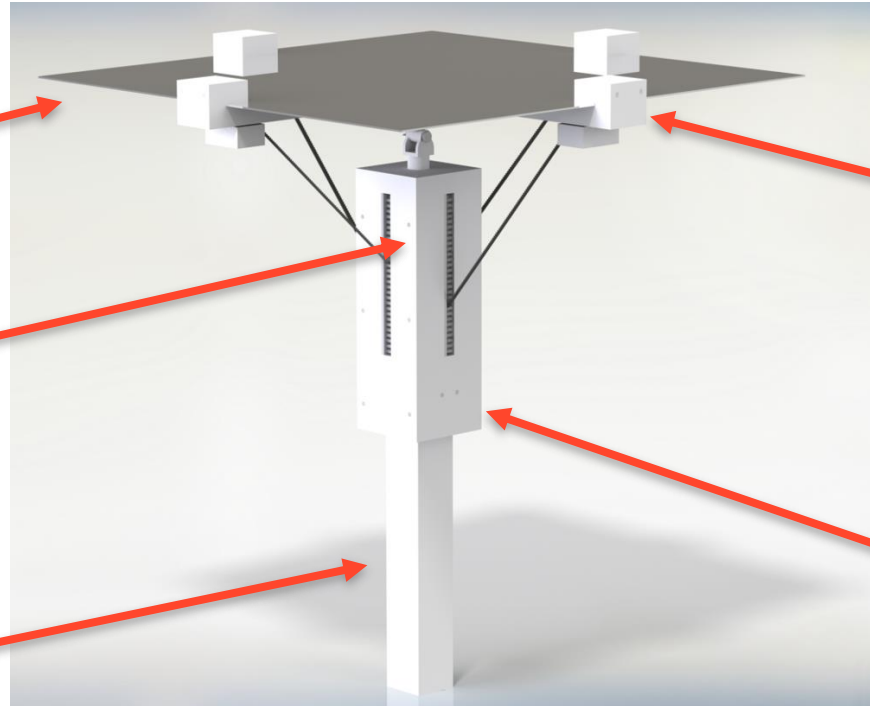
Computer mount and

hardware: **~\$16.81**

(Integrated RISC WIFI board, 24 PPR encoders, motor driver, wiring, fasteners)

Anchor: **~\$5.13**

(custom cut pine wood, fasteners, paint)



Module: **~\$17.42**

(Wood, corner brackets, wood screws, paint)

Support structure:

~\$65.62

(Wood, OTS brush/wood screws/pulley, timing belt, 3D printed u-joint, 6V 6 RPM DC worm gear motors, paint)

Cost Table Summary: Full Assembly

Factor	Estimated Cost (USD)	Source or Justification
Raw materials	126.46	Lowest-cost OTS parts or stock material
Manufacturing	30.40	Gator Motorsports manufacturing costs sheet
Assembly	8.25	Boothroyd and Dewhurst assembly time estimation
Energy Consumption (single-family home)	\$1322.12 / month	Customer, fuel, nonfuel, and demand charge rates from NV Energy

Cost Summary: Facility Energy Consumption

$$C_e = e_c + e_f + e_{nf} + e_d$$

energy cost = customer charge + fuel charge + non fuel charge + demand charge

$$e_c = \frac{\$5.75}{\text{month}}$$
$$e_f = \frac{\$0.08101}{\text{kWh}} * 4798 \frac{\text{kWh}}{\text{month}} = \frac{\$388.69}{\text{month}}$$
$$e_{nf} = \frac{\$0.16}{\text{kWh}} * 1000 \text{ kW} = \$160$$
$$e_c = \frac{\$0.16}{\text{kWh}} * 4798 \frac{\text{kWh}}{\text{month}} = \frac{\$767.68}{\text{month}}$$

Total = \$1322.12/month

Technology Readiness Levels

Technology Readiness Levels

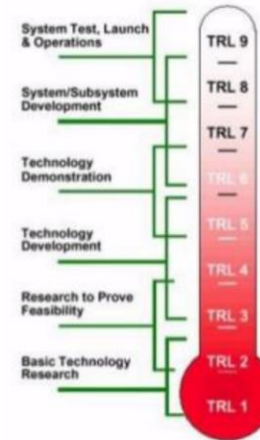
Originally developed by NASA in the 1980s

At this stage, our project is within this range



- Level 1 : Basic principles observed and reported
- Level 2 : Concept and/or application formulated
- Level 3 : Concept demonstrated analytically or experimentally
- Level 4 : Key elements demonstrated in laboratory environments
- Level 5 : Key elements demonstrated in relevant environments
- Level 6 : Representative of the deliverable demonstrated in relevant environments
- Level 7 : Final development version of the deliverable demonstrated in operational
- Level 8 : Actual deliverable qualified through test and demonstration
- Level 9 : Operational use of deliverable

* Level 1: Basic, Level 2: Applied, Level 3: Prototype



Adapted from:
 Martin, Shawn K. "Technology Readiness Levels from a Practitioner's Point of View." 29 Nov. 2021. Lecture.

TRL 3 based on lowest component rating

Why our design?

- Our design offers cheap and readily available material that can be sourced locally.
- Our design is highly manufacturable, requiring minimal tooling to produce.
- Our design is simply operated with little maintenance.
- Easily scalable prototype to downsize



Questions?

